

# GNSS Firmware v4.8p2

# **Release Notes**

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## **Supported Products**

#### **Systems**

- Topcon HiPer SR, GR-5<sup>1</sup>, HiPer V<sup>2</sup>, HiPer II, GRS-1, Net-G3A, MR-1, MC-i3, and MC-i4
- Sokkia GSX2, GCX2<sup>3</sup>, GRX2, GRX1, and GHX2 (Mesa RTK)

#### **OEM Boards**

• B110, OEM-1, Euro 112PII

## **Features and Changes**

- Supported ObsFlags(2) field in BINEX output (all products)
- New support for controlling HTTPS to improve security and stability (Net-G3A)
- Updated antenna database
- Improve satellite tracking in difficult conditions and in presence of moderate interference/jamming (manual calibration required)

<sup>&</sup>lt;sup>1</sup> GR-5 with Vanguard technology now supported by FW 5.1p1 and later.

<sup>&</sup>lt;sup>2</sup> GR-5 (without Vanguard technology), HiPer II, HiPer V, Net-G3A, MR-1, and GRS-1 sales have been discontinued. Service and technical support is still available for these products.

<sup>&</sup>lt;sup>3</sup> Sokkia GRX1, GCX2, GRX2 sales have been discontinued. Service and technical support is still available for this product.

### **Features and Changes from Previous Releases**

Changes introduced in 4.8p1 (Net-G3A only)

• Support ObsFlags(2) field in BINEX output

#### Changes introduced in 4.8

- Incorporates all changes from previous releases (4.7p6, 4.7p7, 4.7p8 and 4.7p10)
- Tuning of DION, Velocity filters, VISOR convergence, Satellite acquisition and tracking algorithms.
- Tuning of default values for positioning engine:
  - o minimum SNR values for GPS and GLONASS L2 signals in RTK changed to 15.
  - o PDOP mask changed to 20
  - o Minimum number of satellites changed to 6
  - Ambiguity fixing level set to extralow
  - Doppler smoothing filter parameter extended to 100 Hz
  - Default value for pos/dion/switch changed to on.
- Message improvements:
  - New extended [Lh] message added to support all constellations (based on original [LH] message)
  - o Extended [ha] message to include HRMS and PRMS values
  - Fixed output of [LE], [LA] and [WO] messages
  - Fixed output of wsmcnt parameter
- Increased acquisition of GPS L2C signal.
- Performance using 100 Hz position update rate improved (applies to specific configurations with OEM boards only)
- Support for Satellite Status Code 61
- Enhanced satellite reacquisition in cases of antenna shadowing.
- Fixed reporting of battery information (HiPer SR only).
- Updated Antenna database
- Fixed UDP data transfer protocol (Net-G3A)
- Improved logic to update base data when reference station changed
- Fixed issue with loss of RTK fixed solution after correction type change when using AIM mode.

#### Changes introduced in 4.7p10

- Fix for BINEX output after GPS week rollover (Net-G3A only)
- Improved firmware performance during leap second and GPS week rollover events.

Changes introduced in 4.7p8<sup>4</sup> (released for Topcon HiPer SR, B110 OEM, Sokkia GSX2, Sokkia GCX2 only)

- Optimized internal memory usage and processor loading for B110 based receivers
- Added protections during firmware installation which restricts installation of firmware on incompatible B110 based hardware.<sup>5</sup>

<sup>&</sup>lt;sup>4</sup> Please see 4.7p8 Release Notes for complete information and compatibility notes.

<sup>&</sup>lt;sup>5</sup> If an incompatibility between B110 based firmware and hardware is identified during installation, the process will be stopped automatically. A power reset will return the receiver to its previous state.

Changes introduced in 4.7p7<sup>6</sup> (released for Topcon BX10 OEM, MC-i4 (BX10), MC-i3 only)

- Improved data backup to memory during receiver reset (HiPer V & GRX2). Also requires installation of Mainboard Firmware v2.3.
- Optimized internal memory usage and processor loading for BX10 based receivers.
- Added protections during firmware installation which restricts installation of firmware on incompatible BX10 based hardware.<sup>7</sup>

Changes introduced in 4.7p6 (released for Topcon OEM-1, MR-1, Euro112PII, Net-G3A only)

- Improved firmware performance during Leap Second and GPS Week Rollover events.
- DION improvements to fix behavior when NTRIP corrections received
- RMS error improvements in Stand-alone and Code Differential engines, as well as for velocities in RTK mode.
- Output of full covariance matrix (SP, SV, AP messages) is enabled for all solution modes.
- Added support for use of mixture of corrections for GPS L2C and GPS P2 simultaneously in RTK.
- Fixed "QZSS L2C quarter cycle" issue when working with non-Topcon bases.
- Improved GLONASS tracking when not visible parameter status is changed.
- PI message was updated to include mmGPS solution indicators.
- New antenna data base version 2.3.6 has been supported.
- New classes are introduced for Trimble, Novatel and Sokkia receivers in order to better handle for GLONASS biases in positioning solution:
  - o TPS for all Topcon receivers
  - JPS for Javad receivers
  - ASHTECH for Ashtech receivers
  - SOK for legacy Sokkia receivers
  - SKA for Topcon/Sokkia receivers new class
  - o SEPT for Septentrio receivers
  - MAGELLAN for Magellan receivers
  - o NOV for Novatel with old firmware (approximately prior September 2016)
  - 2NOV for Novatel with new firmware (approximately after September 2016) new class
  - LEICA for Leica receivers
  - TRIMBLE for Trimble receivers with old firmware (approximately older than 5.11 of 2016)
  - 2TRIMBLE for Trimble receivers with new firmware (approximately 5.11 of 2016 and newer) - new class
  - OTHER for other receivers
  - UNKNOWN if receiver is unknown

<sup>&</sup>lt;sup>6</sup> Please see 4.7p7 Release Notes for complete information and compatibility notes.

<sup>&</sup>lt;sup>7</sup> If an incompatibility between BX10 based firmware and hardware is identified during installation, the process will be stopped automatically. A power reset will return the receiver to its previous state.