

GRS-1 Featuring Vanguard Technology





GRS-1 Operator's Manual

Part Number 7010-0926 Rev B

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Preface

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Manual Conventions

This manual uses the following conventions:

Example	Description			
File ▶ Exit	Click the File menu and click Exit.			
Connection	Indicates the name of a dialog box or screen.			
Frequency	Indicates a field on a dialog box or screen, or a tab within a dialog box or screen.			
Enter	Press or click the button or key labeled Enter.			



Further information to note about the configuration, maintenance, or setup of a system.



Supplementary information that can help you configure, maintain, or set up a system.



Supplementary information that can have an affect on system operation, system performance, measurements, or personal safety.



Notification that an action has the potential to adversely affect system operation, system performance, data integrity, or personal health.



Notification that an action *will* result in system damage, loss of data, loss of warranty, or personal injury.



Under no circumstances should this action be performed.

Notes:

Introduction

The GRS-1 receiver is a dual-frequency, GPS+GLONASS L1, L2 receiver and hand-held controller built to be the most advanced, compact, and portable receiver for the surveying, GIS, and construction markets. This GRS-1 receiver includes an enhanced GNSS receiver board with VanguardTM technology that supports 226 channels¹. An integrated electronic compass and optional digital camera make the GRS-1 an all-purpose device that can also be utilized as a field collector.

The GRS-1 receiver is a multi-function, multi-purpose receiver intended for precision markets. Precision markets means markets for equipment, subsystems, components and software for surveying, construction, commercial mapping, civil engineering, precision agriculture and land-based construction and agriculture machine control, photogrammetry mapping, hydrographic and any use reasonably related to the foregoing.

The GRS-1 can received and process both L1 and L2 signals, improving the accuracy of your survey points and positions. The GPS+ component of GRS-1 receivers means you can access both the GPS (Global Positioning System) satellites of the United States, and the GLONASS (Global Navigation Satellite System) satellites of the Russian Federation, increasing the number of satellites your receiver can detect, thus improving the accuracy of your survey points, increasing productivity, and reducing cost.

The dual-frequency and GPS+ features of the GRS-1 combine to provide the only real time kinematic (RTK) system accurate for short and long baselines. Several other features, including multipath mitigation and Enhanced Positioning Engine (DION), provide undercanopy and low signal strength reception. The GRS-1 provides the

^{1.} For more information, see "Product Identification" on page B-1.

functionality, accuracy, availability, and integrity needed for fast and easy data collection.



Figure 1-1. GRS-1

Principles of Operation

The GRS-1 is a fully integrated hand-held controller and GPS+ GLONASS L1, L2 receiver¹. An integrated electronic compass and optional digital camera make the GRS-1 an all-purpose field mapping unit.

The hand-held controller component of the GRS-1 includes the Windows® Mobile® operating system and color LCD touch screen. Integrated Bluetooth® and Wireless LAN technology allows this system to be a cable-free controller/receiver for maximum portability. The casing is durable and built for rugged use. As a field controller, the GRS-1 can run a full suite of field software for working with total stations and RTK GPS systems.

^{1.} The GRS-1 includes the latest Vanguard ASIC technology and is capable of supporting planned signals for Galileo. Support will be incorporated to the GRS-1 when these constellations have matured and are ready for commercial use.

The GPS+ receiver component of the GRS-1 can receive and process GPS+GLONASS L1, L2 signals, improving the accuracy of your survey points and positions. The receiver's GPS+ features provide a positioning system accurate for any survey. Several other features, including multipath mitigation, provide under-canopy and low signal strength reception. When power is turned on and the receiver self-test completes, the receiver's 226 channels initialize and begin tracking visible satellites. Each of the receiver's channels can be used to track any one of the GPS or GLONASS signals. The number of channels available allows the receiver to track all visible GPS and GLONASS satellites at any time and location.

An internal GPS+GLONASS L1 antenna equipped with a low noise amplifier (LNA) and the receiver's radio frequency (RF) device are connected with a coaxial cable. The wide-band signal received is down-converted, filtered, digitized, and assigned to different channels. The receiver processor controls the process of signal tracking.

Once the signal is locked in the channel, it is demodulated and necessary signal parameters (carrier and code phases) are measured. Also, broadcast navigation data are retrieved from the navigation frame.

GNSS Overview

Currently, the following three global navigation satellite systems (GNSS) offer line-of-site radio navigation and positioning, velocity, and time services on a global, all-weather, 24-hour scale to any user equipped with a GNSS tracking receiver on or near the Earth's surface:

- GPS the Global Positioning System maintained and operated by the United States Department of Defense. For information on the status of this system, visit the US Naval Observatory website (http://tycho.usno.navy.mil/) or the US Coast Guard website (http://www.navcen.uscg.gov/).
- GLONASS the Global Navigation Satellite System maintained and operated by the Russian Federation Ministry of Defense. For

information on the status of this system, visit the Ministry of Defense website (http://www.glonass-center.ru/frame_e.html).

• GALILEO – an upcoming global positioning system maintained and operated by Galileo Industries, a joint venture of several European space agencies working closely with the European Space Agency. Unlike GPS and GLONASS, this is a civil endeavor and is currently in the development and validation stage. For information on the status of this system, visit the Galileo Industries website (http://www.galileo-industries.net).

Despite numerous technical differences in the implementation of these systems, satellite positioning systems have three essential components:

- Space GPS, GLONASS, and GALILEO satellites orbit approximately 12,000 nautical miles above Earth and are equipped with a clock and radio. These satellites broadcast digital information (ephemerides, almanacs, time&frequency corrections, etc.).
- Control Ground stations located around the Earth that monitor the satellites and upload data, including clock corrections and new ephemerides (satellite positions as a function of time), to ensure the satellites transmit data properly.
- User The community and military that use GNSS receivers and the corresponding satellites to calculate positions.

Calculating Absolute Positions

When calculating an absolute position, a stationary or moving receiver determines its three-dimensional position with respect to the origin of an Earth-Center Earth-Fixed coordinate system. To calculate this position, the receiver measures the distance (called pseudoranges) between it and at least four satellites. The measured pseudoranges are corrected for clock differences (receiver and satellites) and signal propagation delays due to atmospheric effects. The positions of the satellites are computed from the ephemeris data transmitted to the receiver in navigation messages. When using a single satellite system, the minimum number of satellites needed to compute a position is four. In a mixed satellite scenario (GPS, GLONASS, GALILEO), the receiver must lock onto at least five satellites to obtain an absolute position.

To provide fault tolerance using only GPS or only GLONASS, the receiver must lock onto a fifth satellite. Six satellites will provide fault tolerance in mixed scenarios.

Calculating Differential Positions

DGPS, or Differential GPS, typically uses the measurements from two or more remote receivers to calculate the difference (corrections) between measurements, thus providing more accurate position solutions.

With DGPS, one receiver is placed at a known, surveyed location and is referred to as the reference receiver or base station. Another receiver is placed at an unknown, location and is referred to as the remote receiver or rover. The reference station collects the range measurements from each GPS satellite in view and forms the differences (corrections) between the calculated distance to the satellites and the measured pseudo-ranges to the satellites.

These corrections are then built up to the industry standard (RTCM or various proprietary standards) established for transmitting differential corrections and broadcast to the remote receiver(s) using a data communication link. The remote receiver applies the transmitted DGPS corrections to its range measurements of the same satellites.

Using this technique, the spatially correlated errors—such as satellite orbital errors, ionospheric errors, and tropospheric errors—can be significantly reduced, thus improving the position solution accuracy of the GPS.

A number of differential positioning implementations exist, including post-processing surveying, real-time kinematic surveying, maritime radio beacons, geostationary satellites (as with the OmniSTAR service), and the wide area augmentation system (WAAS) service.

The real-time kinematic (RTK) method is the most precise method of real-time surveying. RTK requires at least two receivers collecting navigation data and communication data link between the receivers. One of the receivers is usually at a known location (Base) and the other is at an unknown location (Rover). The Base receiver collects carrier phase measurements, generates RTK corrections, and sends this data to the Rover receiver. The Rover processes this transmitted data with its own carrier phase observations to compute its relative position with high accuracy, achieving an RTK accuracy of up to 1 cm horizontal and 1.5 cm vertical.

Essential Components for Quality Surveying

Achieving quality position results requires the following elements:

- Accuracy The accuracy of a position primarily depends upon the satellite geometry (Geometric Dilution of Precision, or GDOP) and the measurement (ranging) errors.
 - Differential positioning (DGPS and RTK) strongly mitigates atmospheric and orbital errors, and counteracts Selective Availability (SA) signals the US Department of Defense transmits with GPS signals.
 - The more satellites in view, the stronger the signal, the lower the DOP number, the higher positioning accuracy.
- Availability The availability of satellites affects the calculation of valid positions. The more visible satellites available, the more valid and accurate the position. Natural and man-made objects can block, interrupt, and distort signals, lowering the number of available satellites and adversely affecting signal reception.
- Integrity Fault tolerance allows a position to have greater integrity, increasing accuracy. Several factors combine to provide fault tolerance, including:
 - Five or more visible satellites for only GPS or only GLONASS; six or more satellites for mixed scenarios.
 - Wide Area Augmentation Systems (WAAS, EGNOS, MSAS, etc.) creates and transmit, along with DGPS corrections, data integrity information (for example, satellite health warnings).
 - Current ephemerides and almanacs.

Conclusion

This overview simply outlines the basics of satellite positioning. For more detailed information, visit the TPS website at www.topconpositioning.com.

GRS-1 Overview

The GRS-1 is a fully integrated hand-held controller and GPS+GLONASS L1 receiver. Integrated into the unit is a 226 channel dual frequency GPS and GLONASS receiver, and electronic compass, digital camera and optional cellular modem for internet connections.

The hand-held controller component of the GRS-1 includes the Windows® Mobile operating system and color LCD touch screen. Integrated Bluetooth® and wireless LAN technology allows this system to be easily connected to other Topcon sensors or wireless networks. The casing is durable and built for rugged use.

As a field controller, the GRS-1 can run a full suite of field software for working with total stations and RTK GPS systems.

The GPS+ receiver component of the GRS-1 can receive and process GPS+GLONASS L1 and L2 signals improving the accuracy of your survey points and positions. The GPS+ features of the receiver combine to provide a positioning system accurate for any survey. Several other features, including multipath mitigation and coop tracking, provide under-canopy and low signal strength reception.

When power is turned on and the receiver self-test completes, the receiver initializes and begins tracking visible satellites. The receiver uses Universal Tracking Channel Technology to track signals from supported constellations. The number of channels available allows the receiver to track all visible GPS and GLONASS satellites at any time and location.

An internal L1 GPS+GLONASS antenna equipped with a low noise amplifier (LNA) and the receiver's radio frequency (RF) device are connected with a coaxial cable. You can use the GRS-1 receiver with an external Topcon PG-S1 antenna to track dual frequency signals from dual constellations. After the receiver locks on to four or more satellites, it is possible to solve the so-called "absolute positioning problem" and compute the receiver's coordinates (in WGS-84) and the time offset between the receiver clock and GPS time. With the collection of enough information to solve for position and time the receiver can solve an RTK position if provided with a differential correction from a base station or network, or the raw observation data may be stored in the optional SD card or to the internal memory of the unit for later post processing with a post-processing software package such as Topcon Tools.

Capabilities of the GRS-1 receiver include:

- Multipath reduction
- Satellite Based Augmentation Systems supported (WAAS, EGNOS, and MSAS)
- Dual-frequency static, kinematic, and Real time kinematic (RTK) survey modes (Use to external GNSS antenna or PG-S1)
- Single-frequency static, kinematic, and differential GPS (DGPS) survey modes
- Setting different mask angles
- Setting different survey parameters

The optional, integrated 2 megapixel camera can be used for taking pictures of surveyed objects or survey sites.

Getting Acquainted with the GRS-1

The GRS-1 is an integrated field controller with a 226-channel GNSS receiver board, an internal electronic compass, and optional internal camera. USB and serial ports, along with Bluetooth® and Wireless LAN provide communication paths with other devices. An external

GNSS antenna connection allows for an optional PG-S1 or PL-S1¹ dual-frequency antenna to be connected for RTK surveying applications.

The standard GRS-1 package contains the following items:

- GRS-1 integrated receiver/controller activated for GNSS L1 signals
- Lithium-ion BT-66Q battery
- Stylus pen
- Power adapter
- USB cable (USB A Mini B) and power adapter cable
- Hand strap, neck strap, and soft case
- Software CD and operator's manual CD
- One-year warranty card

For more details on accessories and options available for the GRS-1, contact your local Topcon dealer.

Rechargeable and Backup Batteries

The GRS-1 comes equipped with a rechargeable battery (Figure 1-2) for powering the unit. The user can charge the battery in the unit or in an optional battery charger. A backup battery is also located in the battery pocket.

The battery provides seven hours of operation, depending on the mode of the receiver. Under normal conditions, the backup battery provides eight to ten years of power backup for data and system integrity. For more information, see "Powering the GRS-1" on page 2-2.

For typical RTK surveying, use the PG-S1 antenna. For decimeter RTK solutions, use the PL-S1 antenna. Contact your local Topcon dealer for more information about receiver configurations suited for your job requirements.



Figure 1-2. GRS-1 Battery

GRS-1 Front

The front of the GRS-1 (Figure 1-3 on page 1-11) is the primary interface with its components and installed software.

- The **internal GPS antenna** detects signals from GNSS satellites and sends them to the GPS receiver board for processing.
- The **display screen and touch panel** provides a graphical and tactile user interface for the unit.
- The **power button** turns the receiver on and off.
- The ESC (escape) button exits from the current screen or function. Pressing this button for one second or more opens the Microsoft Windows Start menu.
- The ENT (enter) button applies settings, numerical values, and records points (depending on the settings of internal software).
- The **Bluetooth LED/Wireless LAN LED** the status of the wireless technology module:

– Blue blink: Bluetooth is on.

- Red blink: wireless LAN is on.
- Violet blink: notification from Windows.
- No light: the module is off.
- The charging LED indicates the level of charge in the battery:
 - Green: battery has a full charge.
 - Red: battery is charging.
 - Red blink: charging error.
- The Cell phone modem LED indicates the receiving status in the cell phone modem.
 - No light: Cell phone is off.
 - Green: Cell phone is available.
 - Red: Cell phone is in dead space.



Figure 1-3. GRS-1 Front

GRS-1 Back

The back of the GRS-1 holds the stylus used for tapping on the display screen. An elastic strap provides comfortable security while using the GRS-1. A cover accesses the rechargeable battery and backup battery.



Figure 1-4. GRS-1 Back

GRS-1 Ports

The GRS-1 has the following three ports:

- USB used for high-speed connection to a computer via ActiveSync.
- Serial used for communication between the internal GPS module (port A of the module) and an external device.
- Power used to connect the GRS-1 to an external power source. This port can also be used to charge the batteries.



Figure 1-5. GRS-1 Ports

SD Card Slot

The SD (secure digital) slot provides extended memory for the controller (Figure 1-6). The user can access the data that resides on the SD card via the USB port, serial port, or Bluetooth® wireless technology. A secure digital card can be purchased at your local computer supply store.

Located above the card slot is the software reset button for restarting the operating system if the software is not responding.



Figure 1-6. SD Card Slot

Integrated Camera

You can use the integrated 2-megapixel camera for taking pictures. The GRS-1 receiver without the camera option is referred to as the GRS-1N receiver. Contact your Topcon dealer for more information about the GRS-1N (without camera).



Figure 1-7. GRS-1 Camera

External GPS Antenna Connector

The external GPS antenna connector allows an optional external antenna to be connected to the controller for RTK and post-process survey applications.



Figure 1-8. GRS-1 External GPS Antenna Connector

System Cables

The GRS-1 package includes standard communication and power cables for communicating with the GRS-1 and providing a power source. Table 1-1 lists the cables included in the standard GRS-1 package.

Cable Description	Cable Illustration		
AC Power cable and adapter Connects the GRS-1 to a grounded outlet. Cable p/n 22-060002-01 Adapter p/n 22-060001-01			
USB cable Connects the GRS-1 to an external device (controller or computer) for high-speed data transfer and receiver configuration. p/n 14-008081-01			

Table 1-1. Gl	RS-1 Pack	age Cables
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GRS-1 Software

The GRS-1 comes with the following factory-installed software:

- BTManager a utility that manages and controls the Bluetooth module inside the GRS-1. BTManager connects the GRS-1 and other Bluetooth-enabled devices. For more information, see "Connecting the GRS-1 and a Bluetooth Device" on page 3-3 and "Using the Bluetooth Manager" on page 5-1.
- Topcon Receiver Utility (TRU) a utility that manages and controls the compass and GNSS settings. For more information, see "Configuring the Receiver" on page 4-1.

• Topcon Communication Manager - TPS Connection Manager is Topcon's tool that comes on the GRS-1 field controller to setup the internal GSM modem for new network connections in Windows Mobile 6.1.

🐉 Bluetooth Man	ager 🚓 式 📢 🗙	🚑 TRU	#	€×	🐉 TPS Connection	n Manager 📰 📢 🗙
Device Name	Address	2/13/09	6:24:48 AM		Connection Name Connection	
321-0194	00:03:7a:4a:43 00:10:c6:2f:08: 00:0e:7b:0d:aa	WGS-84(m) DGPS			Modern Hayes Compatible on	COM1: 🔻
824SH 5000014 5000000000000000000000000000000000000	00:10:ee:c6:ba: 00:02:c7:60:9f: 00:03:7a:22:fd:5f 00:19:79:dd:e5	Lat: 35 : 46 Lon: 139 : 42 Alt: 82.690 PDOP: 1.972	: 25.53914 : 13.20699 m	©0	Operator Name US(AT&T User Name WAP@CINGULARGP APN Wap.cingular	Password ******** Phone *99***1#
Check the checkb that you w < Ba	oxes next to the device ould like to save. ck Next >	HRMS: 0.090 VRMS: 0.183 Position SVs List S	m 💋 m	●3 ●2 Pod ◀ ►	123 1 2 3 4 5 Tab q w e r t CAP a s d f Shift z x c v Ctl áu	67890 • • yuiop() ohjki? bnm, / •
	-				Create	Exit

Figure 1-9. BT Manager, Topcon Receiver Utility, and Communication Manager

Optional Accessories

Table 1-2 gives a brief list of optional accessories that can be used with the GRS-1. Contact your dealer to purchase optional accessories.

Table 1-2	. GRS-1	Optional	Accessories
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Accessory	Illustration
External Single Frequency GNSS Antenna for GIS, and Cable Connecting an external PG-A5 GNSS antenna increases reliability and precision of single frequency solution. PG-A5 p/n 01-844201-07	

Accessory	Illustration
PG-S1 External Dual- Frequency GNSS Antenna for RTK, Data Collection Connecting an external PG-S1 GNSS antenna to your receiver enables survey-grade RTK solutions.	
PL-S1 External Dual- Frequency GNSS Antenna for Sub-Decimeter (Spectrum RTK TM) GIS Mapping Connecting an external PL-S1 GNSS antenna to your receiver enables sub- decimeter RTK solutions.	
Radio Holder Connecting the RH-1 radio holder enables you to transmit/receive correction data for RTK. Contact your Topcon dealer on availability of the RH-1 radio before planning to use it on the job.	
Serial Cable Connects the GRS-1 to an external device (controller or computer) for data transfer and receiver configuration. p/n 14-008080-01	

Table 1-2. GRS-1 Optional Accessories (Continued)

Accessory	Illustration
BR-1 The BR-1 is a receiver that detects signals from local Beacon stations. When connected to the GRS-1, it provides correction data. Contact your Topcon dealer on availability of the RH-1 radio before planning to use it on the job. p/n 01-852001-01	
Lighter Adapter Cable Connects the GRS-1 to an automobile cigarette lighter for power supply p/n 14-008148-01LF	
Serial Cable for Modem Connects the GRS-1 to an external modem. p/n 14-008104-01LF	
Serial Cable for External Receiver Connects the GRS-1 to a Topcon GPS+ receiver. p/n 14-008103-01LF	
Battery Charger Charges the BT-66Q battery. p/n 60565	

Table 1-2. GR	S-1 Optiona	I Accessories	(Continued)
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Accessory	Illustration
Optional Software MAGNET [™] and Pocket- 3D Note: Field Tools for ArcPad, is a discontinued product.	Pecket 30 Pecket 30 129 129 129 129 129 129 129 129

Table 1-2. GRS-1 Optional Accessories (Continued)

Option Authorization File (OAF)

Topcon Positioning Systems issues an Option Authorization File (OAF) to enable the specific options that customers purchase. An Option Authorization File allows customers to customize and configure the receiver according to particular needs, thus only purchasing those options needed.

Typically, all receivers ship with a permanent OAF. When the receiver is purchased, a new OAF permanently activates the desired, purchased options. Receiver options remain intact when clearing the NVRAM or resetting the receiver.

The OAF enables the following functions. For a complete list of available options and details, visit the TopconTotalCare.com website or consult your Topcon dealer.

- GPS/GLONASS L1 signal tracking (At using internal single frequency antenna)
- GPS/GLONASS L1/L2 and GPS L2C signal tracking (At using external dual frequency antenna)
- RTCM Input/Output (standard)
- Satellite Based Augmentation Systems supported (WAAS, EGNOS, and MSAS)

- RTK at 10Hz (standard)¹
- Advanced multipath reduction

Handling Precautions

- Make sure the GRS-1 is functioning correctly with normal performance before using it.
- Always make sure the GRS-1 is dry before putting it in the soft case.
- Do not leave the GRS-1 under strong sunlight for a long time. It may cause the device to malfunction.
- To ensure IP66 weather proofing, make sure that all of the caps are closed securely on the unit. (The external antenna connector has been sealed and will maintain ingress protection from the elements whether cap is closed or not for external antenna operations.)

Storing the GRS-1

- Always clean the GRS-1 after use.
- Use a clean cloth moistened with neutral detergent or water.
- Never use an abrasive cleaner, ether, thinner benzene, or other solvents.
- Always make sure the GRS-1 is completely dry before storing it. Dry any moisture with a soft, clean cloth.

^{1.} Higher output rates are supported and available.

Notes:

GRS-1 Operator's Manual
Preparing the GRS-1 for Use

Before using the GRS-1, make sure the battery is fully charged. If you are using other survey software, such as MAGNET[™] Field or Pocket-3D, install it in the office. Insert an optional SD card before beginning to survey.

Attaching the Hand Strap

The hand strap provides a comfortable, secure support for using the GRS-1 on the job. The velcro extender at the bottom of the strap allows for comfortable re-adjustment of the strap for larger or smaller hands.

To attach the hand strap, thread the bottom end of the strap through the hook on the bottom of the GRS-1 and press the velcro together. Gently stretch the strap, and insert the metal end of the strap into the strap slot on the back of the GRS-1.



Figure 2-1. Attaching the Hand Strap

When replacing the battery, remove the top end of the strap to access the battery door latch.

Powering the GRS-1

The GRS-1 uses a BT-66Q battery for it's primary power source. When using the GRS-1 for static surveys, the battery will last up to four hours. The battery will last up to fifty hours during continuous standby use (that is, no GPS usage, the display LED is off, and the touch screen is not being used). A backup coin battery and rechargeable battery back up the GPS and clock settings.

Installing the Battery

The rechargeable battery can be charged using the power port and AC adapter (see "Charging the Battery" on page 2-3), or either the optional wall charger or cigarette lighter adapter.

To remove/replace the battery (Figure 2-2) do the following:

- 1. If needed, unhook the top of the strap from the GRS-1.
- 2. Open the battery cover, and remove the primary battery. The GRS-1 automatically turns off when the battery cover is opened. When the battery cover is opened, the device automatically switches to suspend mode (power off).
- 3. Replace the battery with a fully charged one, making sure the (+) and (-) symbols on the bottom of the battery are aligned with the symbols in the battery casing.
- 4. Press to close the battery cover until it clicks into place, and reattach the hand strap.



Figure 2-2. Installing the Primary Battery

Charging the Battery

The AC/DC converter AD-11 provides power to the GRS-1 and charges the primary battery. Note that using the GRS-1 while charging increases the charge time. The battery will be fully charged in approximately seven hours.

To charge the battery using the converter

(Figure 2-3 on page 2-4):

- 1. Plug the AC/DC converter connector into the power (DC-IN) port of the GRS-1.
- Plug the converter into a grounded outlet. The Charge LED lights up. The battery is fully charged after about six hours.

The charging LED indicates the level of charge in the battery:

- Green battery has a full charge.
- Red battery is charging.
- Red blink charging error.



It is normal for the GRS-1 receiver to become warm while charging.



Figure 2-3. Charging the Battery in the GRS-1

To charge the battery using the optional charger (Figure 2-4):

1. Remove the battery from the GRS-1 (see "Installing the Battery" on page 2-2 for details), and insert it into the charger.

2. Plug the charger into a grounded outlet.



Figure 2-4. Charging the Battery in the Optional Charger

Charging and Battery Storage Notes

To keep the battery properly charged, maintained, and stored, do the following:

- Only recharge the battery at room temperature, approximately 50°F to 104°F (10°C to 40°C). Charging at a high temperature increases the time it takes to charge the battery.
- Always check the battery charge before using the GRS-1. The battery will discharge during storage.
- Charge a stored battery every seven days. Allowing a battery to become discharged can reduce the overall performance of the battery and charge efficiency.
- Be aware that the charger may become somewhat heated while charging the GRS-1.

Replacing the Backup Battery

The backup battery ensures GPS and clock settings are saved when the primary battery and internal rechargeable battery are depleted. Under normal conditions, the backup battery lasts two to three years.



The Windows Mobile RAM has a separate backup, rechargeable battery. This battery will power the RAM for five minutes after removing the primary battery.

The backup battery is a CR2032 coin battery that can be purchased at many general retailers. You will need Phillips-head and flat-head screwdrivers to replace the backup battery. Follow these steps to replace the backup battery as shown in (Figure 2-5).

- 1. Open the battery cover and remove the primary battery.
- 2. Using a Phillips-head screwdriver, remove the coin battery/SIM card cover.
- 3. Using a flat-head screwdriver, insert the tip of the screwdriver in the slot to the left of the coin battery. Gently push the coin battery to the right to pop it out of the holder. Repeat these steps on the left side of the holder to remove the coin battery.



Replace the battery within a couple of minutes to prevent data loss.

- 4. Insert the new coin battery, plus side up, into the holder. Slide the coin battery under the tabs and gently push into place.
- 5. Replace the coin battery cover and screw.



Figure 2-5. Replacing the Coin Battery

Starting the GRS-1

To start the GRS-1, briefly press the power button. The touch screen lights up, and the GRS-1 splash screen displays while the system loads, and then the Microsoft Windows Mobile desktop displays.



Figure 2-6. Press Power to Start the GRS-1

Calibrating the Touch Screen

The touch screen needs to be calibrated when first starting the GRS-1 or after a hard reset. The configuration function automatically starts and is simple to complete.

1. On the main screen of the GRS-1, press the Start 💐 icon.

2. Press Settings > System tab > Screen



Figure 2-7. Stylus Properties

- 3. Press Align Screen.
- 4. Press and hold the stylus on the center (+) of the cross lines (targets) as it moves about the screen.



Figure 2-8. Calibrate the Touch Screen

5. Once the target stops moving and the device is recalibrated, press **OK** at the top of the screen.

Setting the Power Management

The power management feature prevents battery depletion by automatically conserving the power through the Standby (no GPS usage, the display LED is off, and the touch screen is not being used) or Suspend (power off) mode when the unit is left turned on.

To set the Standby or Suspend mode:

- 1. On the main screen of the GRS-1, press the Start 💐 icon.
- Press Settings ▷ System tab ▷ Power. The Power Properties window appears with the Advanced tab open.

ಶ Se	ttings		÷	€	ok
Power					
On bat	ttery powe m off device d for	r: if not	1 minut	te	•
On ext	ternal power n off device ed for	er: if not	5 minut	tes	Y
Battery	Advanced	External	Backup	RTC	

Figure 2-9. Power Properties

- Check the On battery power: Turn off device if not used for check box, and then select a time from the drop-down menu. Repeat for the On external power: Turn off device if not used for check box and drop-down menu.
- 4. Press **OK** at the top of the screen.

Installing Software

The GRS-1 runs the standard Microsoft® Windows® Mobile® operating system and applications. When installing other software applications onto the GRS-1, Microsoft ActiveSync (Windows XP, 7, or 8 and earlier operating systems up to Windows 98) or Windows Device Center (Windows Vista) is required. The following software may be useful for taking full advantage of the integrated features found in the GRS-1 controller/receiver:

- MAGNET Field full-featured data collection software used on a hand held controller. MAGNET Field is structured into several modules to provide the user with a scalable, cost effective application that can be utilized for all Surveying tasks. Use MAGNET Field to measure and capture rich survey data sets with all types of Topcon sensors.
- Topcon Receiver Utility (TRU) a utility that configures GPS and DGPS receivers connected to a hand-held controller.
- Additional software, such as Pocket-3D and eGIS, are also available to run on your receiver. Contact your Topcon dealer for more information about this and other compatible software.

Installing software onto the GRS-1 requires a connection to a computer that contains the software. Software is first downloaded onto a desktop/laptop computer, then installed onto a connected controller via Microsoft ActiveSync.

Refer to the corresponding manual for specific instructions to install software onto the GRS-1.

Installing Microsoft ActiveSync ActiveSync or Windows Device Center is available for free from the Microsoft website (www.microsoft.com) and must be installed on the computer before installing software onto the GRS-1.

Installing an Optional SD Card

SD (secure digital) cards can be purchased at a local computer supply store. When inserted into the GRS-1, an SD card provides additional data storage, as well as data transfer. The GRS-1 supports SD/SDHC cards with up to 32 GB capacity.

- 1. Open the SD card slot door.
- 2. Gently insert an SD/SDHC card into the slot as shown in Figure 2-10.
- 3. Close the SD card slot door.



Figure 2-10. Insert SD Card

Notes:

Using the GRS-1

The GRS-1 can be used as a stand-alone L1 hand held receiver for mapping or with the external PL-S1/PG-S1 antenna as a dual frequency RTK rover. When installing software or performing file transfers, the USB cable or Bluetooth module connects the GRS-1 to a computer for in-office processing. The GRS-1 can also be used as a controller for other Topcon measurement devices such as manual and robotic total stations, digital levels, and dual frequency receivers.

Connecting the GRS-1 with Other Devices

The GRS-1 provides for direct connection to devices with either a mini serial or USB port, devices that support Bluetooth and wireless LAN operations, or with an external GNSS antenna (PG-S1, PL-S1 or PG-A5), as well as an optional internal cellular modem for network connections for either differential corrections or pushing data to the internet. The various devices are optional and can be purchased from your local Topcon dealer or at a commercial retail store for commercially sold products (such as the SD card).

Connecting the GRS-1 and a Computer

Connecting the GRS-1 and a computer allows you to install software onto the controller and upload data from the controller to a computer.

1. Before connecting the GRS-1 and a computer, make sure Microsoft ActiveSync is installed on the computer. See "Installing Software" on page 2-10 for details.



For a Bluetooth connection, see "Connecting the GRS-1 and a Bluetooth Device" on page 3-3 for details.

2. Connect the GRS-1 and the computer using the interface cable F-25 (USB) or Bluetooth wireless technology.



Figure 3-1. Connect GRS-1 and Computer (USB) Using Cable

- 3. When ActiveSync on the computer prompts to set up a partnership, select **No**, and click **Next**.
- 4. Once the connection has been established, click the **Explorer** icon on the ActiveSync screen to view data on the GRS-1 on-board memory.

About ActiveSync and Windows Mobile Device Center

If you are using the Windows 2000 service pack 4 or Windows XP operating system, then download ActiveSync from the Microsoft website and install it to your computer. If you are using the Windows Vista operating system, then download Windows Mobile Device Center from the Microsoft website and install it on your computer.

The method for downloading and installing ActiveSync and Windows Mobile Device Center is described at the following URL: www.microsoft.com/windowsmobile

- ActiveSync 4.2 and 4.5 is supported by Windows 2000 service pack 4 and Windows XP, 7, or 8.
- Windows Mobile Device Center 6.1 is supported by the Windows Vista operating system.

See the help section of the software for details on how to set up and use the software. If a connection is not possible with your computer, see the Microsoft website (http://support.microsoft.com/kb/259369) or contact the support center for the computer you are using.

Connecting the GRS-1 and a Bluetooth Device

The GRS-1 is equipped with Bluetooth capability, so you can transmit data wirelessly between equipment. The Bluetooth Devices screen displays the List of Favorite Devices, so you can quickly and easily connect with a saved device. If the device you are looking for is not listed, then you can search for up to nine other Bluetooth-enabled devices within range. Make sure the devices you are searching for are discoverable.

To connect with a paired device:

 From the Bluetooth Devices screen, highlight a device, and press Device ▶ Pair.



Figure 3-2. Bluetooth Devices - Select

If you cannot find a saved device on this screen, then press Tools
Device Discovery. An hourglass appears while BTManager searches the List of Favorite Devices and then searches for up to nine nearby Bluetooth-enabled devices.



Figure 3-3. Bluetooth Devices - Discovery

3. After the devices are found, you select a device, and tap **Next**. You can choose more than one device.

A confirmation message appears when the devices are successfully added to the **List of Favorite Devices**.



Figure 3-4. Bluetooth Devices - Pairing

- 4. Pairing Bluetooth Devices
 - Select a device on My Bluetooth Device Screen.
 - Press Device > Pair
 - Enter the pass key.

If an error message displays upon trying to connect, then it usually means that the security settings of the remote device do not correspond to the security settings of the GRS-1.

To correct this, make sure the **Pass Key**, **Authentication**, and **Encryption** check boxes on the **My Bluetooth Device** screen correspond with the security settings of the remote device.

For more information about troubleshooting error messages, see "Bluetooth Problems" on page 7-7.

For more information about connecting devices and using Bluetooth Manager, see "Using the Bluetooth Manager" on page 5-1.

Notes:

Configuring the Receiver

The sections in this chapter describe receiver options and how to load a new Option Authorization File (OAF), update firmware, and manager settings on the internal compass. To do this, use the Topcon Receiver Utility (TRU) software that comes pre-installed on your receiver. For more information about TRU, see the *TRU Operator's Manual* that is available on TopconTotalCare.com and on TopconPositioning.com.

Setting the Receiver's Power State

The Topcon Receiver Utility (TRU) comes pre-installed on your receiver and enables you to configure and manage various receiver functions.

To configure the internal GNSS receiver board, set the board's current power state to ON.

To verify the current power state:

1. Open TRU on your receiver, and click **Device** > **GRS Tools**.

2. Make sure **ON** is selected as the **Current Power State** (Figure 4-1).



Figure 4-1. TRU – Current Power State is ON

Viewing Receiver Information

In the Topcon Receiver Utility (TRU) the **Receiver Info** window displays basic receiver information, such as hardware and firmware versions, RAM size, the receiver ID, the serial number, etc.

To open the Receiver Info window:

- 1. Open TRU on your receiver, and click **Device** > **GRS Tools** to ensure **ON** is selected as the **Current Power State**.
- 2. Click Device > Application Mode > Receiver Managing.
- 3. Click **Device** > Connect.
- 4. In the **Connection Parameters** window (Figure 4-2), do the following:
 - 1. Select **Serial Port** as the type of connection you are using.
 - 2. Select the port you are using, either COM6 or COM7.

3. Click Connect.

ಶ TRU	,#‡. + € ×
Connect Using	
Serial Port	•
Port Name	
COM6: (GNSS Port B)	
Receiver Port-	
External Receiver	
ser/a	~
	•
Connect	

Figure 4-2. TRU – Connection Parameters Window

4. In the TRU main window, click the **Information** icon. The **Receiver Info** (Figure 4-3) window appears.

NRU 🔁	₩ 👫	×
Name	Value	•
I Model	BX10	
≪≱Id	ENHN49PKDTS	
Serial Number		
⊲ Board Version	BX10	
Irmware Version	3.3 GRS Dec,30,2008 b	
Iardware Version	120	=
≪≫ Vendor	Topcon	
CPU Freq., MHz	216	
🛲 RAM Size, KB	16,384	
🔊 Power Supply, V	0.00	•
	•	
Refresh	Save to File	e

Figure 4-3. TRU – Receiver Info Window

Loading New Firmware

The receiver board firmware is released as a compressed file that you download and decompress. This file contains the following two files:

- ramimage.ldr the receiver board RAM file
- main.ldp the receiver board Flash file.

To upload firmware files to the receiver:

- 1. Open TRU on your receiver, and click **Device** ► **GRS Tools** to make sure **ON** is selected as the **Current Power State**.
- 2. Click Device > Application Mode > Receiver Managing.
- 3. Click **Device ▶** Connect.
- 4. In the **Connection Parameters** window (Figure 4-4), do the following:
 - 1. Select **Serial Port** as the type of connection you are using.
 - 2. Select the port you are using, either COM6 or COM7.
 - 3. Click **Connect**.

NTRU	<i>#</i> : +€ ×
Connect Using	
Serial Port	•
Port Name	
COM6: (GNSS Port B)	
Receiver Port	
External Receiver	
ser/a	~
Connect	

Figure 4-4. TRU – Connection Parameters Window

5. Click Device > Application Mode > Firmware Loader.



Figure 4-5. TRU – Firmware Loader

6. Click the **Firmware** icon. The **Upload Firmware** window appears (Figure 4-6). This window enables you to upload firmware files to the connected receiver.

NTRU	# * +€ ×	
Device-		
Receiver/Modem/Bluetooth	•	
r Firmware		_
Loader: usiness\ramimage.ldr		Browno Joono
Image: nts\Business\main.ld	>	
Capture Method		-
Soft Break	•	
- A	Start	

Figure 4-6. TRU – Upload Firmware Window

- 7. Make sure **Receiver/Modem** is selected in the **Device** field.
- 8. (*Recommended*) Select Soft Break as the Capture Method.
- 4. Click the **RAM Image** (.ldr) Browse icon to select the RAM file.
- 5. Click the Main Flash (.ldp) Browse icon to select the Flash file.
- 6. Click **Start** to upload the selected files.

7. Click **OK** to continue uploading new firmware to the receiver (Figure 4-7).

考 TRU		\$\$ ₩ ×		
Device-				
Receiver/	Modem/Bluetooth	•		
[Firmware				
Loader:	usiness\ramimage.ldr	\triangleright		
Image:				
Capture N	1ethod			
Soft Brea	k	•		
Capturing the Device				
Start				

Figure 4-7. TRU – Uploading Firmware

About the OAF

Topcon issues an Option Authorization File (OAF) to enable the specific options that you purchased. Topcon's OAF system allows you to customize and configure the receiver according to particular needs; therefore, purchasing only the options you require.

The GRS-1 receiver ships with an OAF; however, there are several upgrade options available that can extend the receiver's functionality to better suit your job requirements.

Examples of upgrade options include:

- GPS+GLONASS dual frequency 10 Hz Network RTK operation
- GPS+ GLONASS dual frequency static operating
- RTK and update rate at 20 Hz or higher

Contact your Topcon dealer for a complete listing of available options and pricing information.

Checking the Receiver's OAF

- 1. Make sure TRU is installed on your receiver. (Double-click the TRU.exe or TRU executable icon on your receiver.)
- 2. Open TRU, and click **Device** ► **Application Mode** ► **Receiver Managing**.
- 3. Click **Device ►** Connect.
- 4. In the TRU main window, click the **Options** icon. The **Receiver Options** window appears (Figure 4-8), so you can view the current authorization options and upload new ones.



餐 TRU		_ ₽ +	i€ ×
Friendly Name		Inte	Cu 🔺
GPS GPS		_GPS	Yes
GLONASS		_GLO	Yes
🚺 L1		_L1_	Yes
E1 [12		_L2_	Yes
🚺 Cinderella		CIND	Yes
Position Upd	late Rate, Hz	_POS	20
👔 Raw Data U	pdate Rate, Hz	_RAW	20
Code Differential Base		CDDB	Yes
Code Differe	ential Rover	CDDR	Yes
RTK Base		RTKB	Yes
RTK Rover,	Hz	RTKR	20
Memory, MB		_MEM	No 🕶
▲ ■			
Refresh	Save t	o File	
			_

Figure 4-8. TRU – Receiver Options Window

Loading an OAF

- 1. Follow the steps in "Checking the Receiver's OAF" on page 4-7.
- Click Upload OAF in the Receiver Options window (Figure 4-8).
- 3. Locate and select the new Option Authorization File, and click **OK** (Figure 4-9).



Figure 4-9. TRU – Locating an OAF

TRU takes a moment to verify the selected file is compatible with the connected receiver. If the selected file is not intended for this receiver,

the **Upload OAF** window displays an error icon next to the Receiver ID and disables the **Upload the File to the Receiver** button.

🚝 TRU	₽ # * ⊀€	💦 TRU	₽ # * + € ×
Open		\My Documents\	Business_UNIVERSAL_2_
Folder: All Folders Type: Options Files Name Fo	Cancel (*.tpo) Ider Date siness 2/6 8:17 AM	Property Owner SerialNo ReceiverID Model Checksum Dealer Email SubmitTime Cipher	Value NA XX-XXXXXXX-XX Universal Le C19E Topcon Positioning Systems 2013-02-06 15:21:18 Digest
		Upload	the File to the Receiver

Figure 4-10. TRU – Uploading an OAF

4. Press **Upload the File to the Receiver** (Figure 4-10) to begin uploading the file. When an OAF is uploaded to the receiver, TRU offers to reset the receiver to put the new authorization options into operation (Figure 4-11).

💕 TRU 🦹 👫 📢
\My Documents\Business_UNIVERSAL_2_
Ontion Name Result
The changes will take effect after reset. Reset the receiver?
Yes No
Upload the File to the Receiver
and a second

Figure 4-11. TRU – Reset the Receiver

Performing a Factory Reset (Clearing the NVRAM)

The receiver's Non-Volatile Random Access Memory (NVRAM) holds data required for satellite tracking, such as ephemeris data and receiver position. The NVRAM also keeps the current receiver's settings, such as active antenna input, elevation masks and recording interval, and information about the receiver's internal file system. Clearing the receiver's NVRAM restores the receiver's factory default settings.

Although clearing the NVRAM is not recommended as a common practice, there are times when it can eliminate communication or tracking problems.

After clearing the NVRAM, the receiver requires time to collect new ephemerides and almanacs (around 15 minutes).

Clearing the NVRAM will not delete any files already recorded in the receiver's memory, and the NVRAM keeps information about the receiver file system.

To clear the NVRAM:

- 1. Connect the receiver to a computer, and open the Topcon Receiver Utility (TRU). See the *TRU Reference Manual* for more information about connecting the receiver to a computer.
- 2. In TRU, click **Device** ► **Application Mode** ► **Receiver Managing**.
- 3. Click **Device ▶** Connect.
- 4. In the **Connection Parameters** window, select the appropriate parameters, and click **Connect**.

5. In the TRU main window, press the **Tools** icon. The **Tools** window appears (Figure 4-12), enabling you to reset the receiver and clear the NVRAM.

🎥 TRU		#‡ 4 € ×
	Reset Receiver	
	Factory Reset	
	Reset Parameters	
	Reset RTK	
	Power Off	
	Sleep	

Figure 4-12. TRU – Clearing the NVRAM

6. Click Factory Reset, and then Yes to continue (Figure 4-13).



Figure 4-13. TRU – Clearing the NVRAM Confirmation Window

Using the Compass

Press Start > TRU > Device > GMS/GRS Tools.

The Compass tab displays the current direction, roll, and pitch of the GRS-1. This tab also calibrates the compass.

- Pointer North (red portion of pointer) and South (black portion of pointer) directions.
- Angle the angle (azimuth) from North, in degrees.
- Tilt the roll and pitch, from level, in degrees minutes.



Figure 4-14. View the Compass

Declination is the angle between magnetic north and true north. The compass shows magnetic north. In order to determine the coordinates, it is necessary to correct the declination.

Inclination is downward in the northern hemisphere. Because the compass detects the horizontal component of a magnetic field, azimuth accuracy worsens in the high magnetic area where a magnetic horizontal component is small.

The compass function can be used in the area within +/- 70 degrees magnetic latitude.

Magnetic Field Distortions occurs near ferrous materials and material that disturbs a magnetic field, such as:

- The inside and surrounding area of a railroad, car, and ferroconcrete building.
- A magnet, motor, and electric products, including digital camera, personal computer, data collector, etc.
- The surrounding area of a plant that induces a magnetic field like a high-voltage line and substation.
- The surrounding area of a metal (iron, nickel, and cobalt) mine.
- A wrist watch. (Keep a distance of 15 cm or more between the GRS-1 and a wrist watch.)

Because azimuth accuracy worsens near ferrous materials as described above, correct the azimuth by methods other than magnetism. For example, you can:

- Determine the coordinates of two points from the DGPS function. (The distance of two points must be 120 m or more.)
- Determine the right azimuth from two known points on a map.



Do not use an AC/DC adaptor at the time of compass use.

Calibrating the Compass

Calibrate each location before starting the measurement for an accurate value.

When the unit is turned on, the previous calibration will be used. See also "Recalibrating the Compass" on page 4-16.

To calibrate the compass:

7. Open TRU, and press **Device** ► **GMS/GRS Tools** ► **Compass** tab.



Figure 4-15. Compass Tab

8. Press **Calibrate**, and then start the calibration as shown in Figure 4-16.



Figure 4-16. Begin Compass Calibration

- 9. Hold the GRS-1 horizontally in your hand and turn to any direction.
- 10. Rotate the device 360 degrees in a horizontal direction for five or more seconds. See Figure 4-17.

- 11. Rotate the device 360 degrees in a roll direction for five or more seconds. See Figure 4-17.
- 12. Rotate the device 360 degrees in a pitch direction for five or more seconds. See Figure 4-17.
- 13. Turn your body 90 degrees in any direction, and repeat steps 4, 5, and 6.



Figure 4-17. Calibrating the Compass

14. Press OK.

If calibration is successful, the *Calibration completed successfully* window appears, and the calibration value is saved. Press **OK**.



Figure 4-18. Calibration Successful

If you did receive an error message, then you may have rotated the device too quickly or in the wrong direction. Try to recalibrate the compass.



Figure 4-19. Calibration Error

If a calibration error appears several times, change the direction a little and try again.

Recalibrating the Compass

Recalibration is needed in the following cases:

- The survey location changes frequently.
- The GRS-1 receives a shock, such as being dropped.
- The temperature changes 10 degrees or more.
- The device is transported by car or airplane.
- The device is attached to metal objects, such as a tripod and a pole.
- The battery is exchanged.
- The magnetic field changes, such as an approaching car.
- The device is near a strong magnetic object or material, such as a permanent magnet, electromagnet, motor, transformer, AC power supply, speaker, etc.

Using the Camera

To take a picture:

- 1. Press Start > Pictures & Videos.
- 2. Press the **Camera** icon.

Pictures & Videos		\$\$ ₩ ¥	🚑 Pictures & Vid	eos 🚓 🕂
		Date 🗸		
Camera				
	e la		>	
				9999 Q 1
Camera		Menu	Thumbnails	Menu

Figure 4-20. Take a picture

- 3. Aim the camera at the desired object(s), using the finder/review pane to frame the image.
- 4. Press the **ENT** key on the GRS-1 to take the picture.
- 5. Press Thumbnails.

6. Check to save the picture.



Figure 4-21. Save a picture

Adjust camera settings using the following selections:

Press Menu on the camera finder screen.

- Brightness Select a brightness of the captured image. Settings are from -3 to +3.
- Resolution select the resolution in bits of the image to capture. Settings are from 160x120 to 1600x1200.
- Zoom select the scaling factor. Settings are from zoom 1 to 4.



Figure 4-22. Adjust Camera Settings
To set the macro and long distance modes: turn the dial to the left for macro mode and to the right for long distance mode as shown in Figure 4-23.





Figure 4-23. Camera Dial Modes

Notes:

Using the Bluetooth Manager

The BTManager utility controls the GRS-1 Bluetooth module.

Getting Started

To start BTManager:

- 1. Turn on the GRS-1.
- 2. Press the Bluetooth icon in the system tray, and select **Bluetooth Manager** from the pop-up menu.



Figure 5-1. Starting Bluetooth Manager

3. If the Bluetooth transmitter is switched off (The Bluetooth icon is gray.), select **Turn Transmitter On** to turn on Bluetooth.

Getting Acquainted

Table 1-1 summarizes the screens and settings in BTManager.

Description	Screen	
Type of devices to detect		
This screen displays types of devices to discover. Once a device type is selected, the Discovery Wizard searches for those devices when you tap Next .	Wetwork Manager Image: Im	
Device List		
This screen displays all discovered devices of a selected type. From this list, you can choose a device to add to your List of Favorite Devices by tapping Next .	Bluetooth Manager Image:	
	Nume i	

Table 5-1. BTManager Screens

Description	Screen
List of Favorite Devices This screen displays your preferred Bluetooth-enabled devices. You can use the Device Discovery wizard option in the Tools menu or the Bluetooth Devices screen to search for Bluetooth-enabled devices within range and save them to this list for future connections.	Bluetooth Manager # ★ Image: Second Hold State Image: Second Hold State Image: Second Hold State TopconHQ1 321-0194 447-00624
My Bluetooth Device This screen displays the internal GRS-1 Bluetooth module information. On this screen, you can set your preferences and choose how to connect with other devices.	Device View Tools Help Image:

Table 5-1. BTManager Screens (Continued)

Description	Screen
Pairing This screen displays when the GRS-1 is in pairing mode, and it accepts a pairing request initiated by a remote device.	Bluetooth Manager C X Bluetooth Device Pairing Tap Next to begin pairing Bluetooth devices. Pairing creates a bond between the computer and your Bluetooth device. This process is only required once per Bluetooth device. Kest >
Bluetooth Devices	
This screen displays the List of Favorite Devices. If you do not see a device that you are looking for on this list, then you can tap Find to search for it.	Bluetooth Manager Image:
	Image: Constraint of the second se

Table 5-1. BTManager Screens (Continued)

Description	Screen		
About BTManager			
About B I Manager This screen displays version and copyright information for BTManager.	Start Image: Constraint of the second se		
	Calendar Contacts		

Table 5-1. BTManager Screens (Continued)

Working with Bluetooth Manager

Before the GRS-1 can pair with another Bluetooth-enabled device, it must discover which devices are available within your coverage area. You can use the Device Discovery wizard to search for any Bluetoothenabled device within range or a particular type of device, and then save the device(s) to your Bluetooth Devices folder for future connections.



Figure 5-2. List of Favorite Devices

Discovering Devices

To discover other Bluetooth-enabled devices within your coverage area.

1. Tap **Tools ▶ Device Discovery.**

The Discovery Wizard appears (Figure 5-3).



Figure 5-3. Discovery Wizard

2. Tap Next to display a list of device types.



Figure 5-4. Device Categories

3. Choose a type of device to discover, and tap Next.

The Discovery Wizard searches for Bluetooth-enabled devices in your coverage area and displays the icons of the devices it detects on the **Device List**.

As device names and addresses are retrieved, the Device List updates with detailed information (Figure 5-5 on page 5-8).

Once the Device List is populated, you can add any device from this list to the List of Favorite Devices.



Only up to nine devices can be discovered at a time. If you select the "Any Bluetooth device" option and the device you want is not displayed in the *Device List* (Figure 5-5 on page 5-8), then select a more specific category to narrow the range of the devices you want to discover.

Adding to the List of Favorite Devices

The *Device List* displays all discovered Bluetooth-enabled devices in your coverage area.

To add a device from the Device List to the *List of Favorite Devices*:

1. Select a device, and tap **Next**. You can choose more than one device.



Figure 5-5. Select Device(s)

A confirmation message appears when the devices are successfully added to the **List of Favorite Devices**.

2. Tap **Finish** to exit the *Wizard* and display the **List of Favorite Devices**.



Figure 5-6. Devices Added

To save time, you can save Bluetooth-enabled devices on the **List** of Favorite Devices, so you do not have to rediscover it. You can view devices by icon and name or by name and address.

🐉 Bluetooti	Bluetooth Manager		- # +€ ×		×
8	2	₿	*)	
TopconHQ1	321-	0194	447-00	624	
	Dev	rice Dis	covery		
Device View	Tools	Help			1 ^

Figure 5-7. List of Favorite Devices

To display the list of devices by name and address, tap **View ▶ Details**.

对 Bluetooth Manag	ger 🕂 ┥╡ 🗙		
Device Name	Address		
FopconHQ1	00:03:7a:22:fd:5f		
321-0194	00:10:c6:2f:08:d5		
8 447-00624	00:03:7a:4a:43:85		
▲ ■	•		
Device View Tools Help			

Figure 5-8. Details on Bluetooth Devices

Viewing Device Properties

To view the properties of a device, select the device in the **List of Favorite Devices** (Figure 5-7 on page 5-9), and tap **Device** > **Properties**.



Figure 5-9. Bluetooth Device Properties

The *Bluetooth Device Properties* screen displays major and minor class identifiers, the name, and address of the selected device.

Deleting a Device from the List

To delete a device from the List of Favorite Devices:

- Select the device, and tap **Device ➤ Delete**.
 A confirmation message appears.
- 2. Tap **Yes** to delete the device.



Figure 5-10. Deleting a Device

Setting Device Preferences

The **My Bluetooth Device** screen (Figure 5-11 on page 5-12) displays information about the internal GRS-1 Bluetooth module. The preferences you set on this screen determine how your GRS-1 pairs with and connects to remote devices.

To access the My Bluetooth Device screen, tap **Device** > My **Bluetooth Device**.



Figure 5-11. My Bluetooth Device

My Bluetooth Device always displays the following information:

- Class (major and minor)
- Name (Other devices use this name to identify the GRS-1.)
- Address

This screen also allows you to enable the following accessibility options:

- Discoverable: allows other devices within range to find the GRS-1.
 - It is not necessary to enable this option when initiating a connection from the GRS-1 and for most dial-up networking.
 - When not in use, disable this option manually to save power.
- Connectable: allows other devices within range to connect to the GRS-1.
 - It is not necessary to enable this option when initiating a connection from the GRS-1 and for most dial-up networking.
- Authentication: authenticates the identity of other devices. Select this option if you want to require a passkey to connect with another Bluetooth enabled device. If either or both devices use

authentication, then a passkey must be entered. Once Authentication is selected, the Passkey can be edited.

• Encryption: secures all data sent over Bluetooth.



Typically, Topcon Bluetooth-enabled GPS receivers do not require a PIN upon connection. If it is necessary, however, the PIN (up to 16 characters) can be set for a Topcon GPS receiver by BTCONF, the Topcon Bluetooth module configuration program.



Topcon Total Stations require a PIN on connection. Typically, the PIN value is set to "1111". This value can be changed.

- Service Mode: BTManager allows the GRS-1 to connect with other Bluetooth-enabled devices using serial port or dial-up services. The connecting device needs to support the service selected:
 - SPP (Serial Port Profile): provides serial port connection with peripheral Bluetooth-enabled devices, including GPS receivers which normally do not require authentication.
 - DUN (Dial-up Networking Profile): provides a standard to access dial-up services over Bluetooth. The most common scenario is using a mobile phone as a modem.

Pairing Bluetooth Devices

The Pairing Mode allows a remote Bluetooth-enabled device to initiate a request to pair with the GRS-1. If the Pairing Mode option is activated, then the GRS-1 switches to Pairing Mode for two minutes. During this two-minute period, any remote device can attempt to pair with it.

The GRS-1 accepts the first pairing request if the security settings on the remote device match the GRS-1 security settings. You do not need to activate the Pairing Mode option if the GRS-1 initiates the pairing request.



To activate Pairing Mode, tap **Device** > **Pair**.

Figure 5-12. Device Menu - Pairing Enable

The **Pairing** screen appears, displaying how much time is left to pair with another device.



Figure 5-13. Pairing Mode

Once the two minutes expires, a message appears stating if the pairing succeeded or failed.



Figure 5-14. Pairing Confirmation

For information about connecting Bluetooth Devices, see "Connecting the GRS-1 and a Bluetooth Device" on page 3-3.

For information about troubleshooting Bluetooth error messages, see "Bluetooth Problems" on page 7-7.

Notes:

TPS Connection Manager

TPS Connection Manager is Topcon's tool that comes on GRS-1 field controller to setup the internal GSM modem for new network connections in Windows Mobile 6.1.

The tool includes the following functionality:

- Power on the modem and dial based on settings.
- Define the settings for new network connection.
- Power on the GPS receiver.

To run the tool, tap the TPS Connection Manager start icon in the lower right corner of the Windows Mobile screen that opens upon turning the GRS-1 on.



Figure 6-1. Start TPS Connection Manager

Tapping the TPS Connection Manager icon brings up the Main Menu.

Main Menu

The Main Menu displays the menu to access the main options available in the TPS Connection Manager.



Figure 6-2. Main Menu

- Cellular power on turns on the cell phone power.
- *Resume cellular power* if this Resume function for the internal GSM is ON (checked with a tick), the GSM power state is automatically restored when the GRS-1 is turned on.
- *Data connection* sets up network connections to the best available for "My ISP". It is grey out when the GSM power is OFF.
- Create new connection entry adds new network connections.
- GPS Receiver Power turns on the GPS receiver power.
- About this will show the TPS Connection Manager version.

Create New Connection

When selected, the *Create new connection entry* option will open the dialog to enter settings for a new network connection.

Create New —	🎥 TPS Connection	Manaç 🗹 💭 🕂 🗙	
Connection Entry	Connection Name		
	Connection 2		
	Modern		
	Hayes Compatible on COM1: 🔹 👻		
	Operator Name		
	Russia/MTS		
	User Name	Password	
	mts	11111	
	APN	Phone	
	internet.mts.ru	*99****1# ▼	
	123 1 2 3 4 5 6	7890-==	
	Tablowleirit	v u i o p []]	
	CAPasdfg	h j k ; '	
	Shift z x c v ł	o n m , . / ↔	
	Ctl áü ` \		
	Create	- Exit	

Figure 6-3. Create New Connection Entry

- Connection Name the new connection name.
- *Modem* selects the modem type from the predefined list. The default selection is preferable.
- Operator Name selects the operator from the predefined list.
- *User Name, Password, APN, Phone* these will set the user name, password, Access Point Name (APN) and phone dial number to log on to the remote network. The dial number can be edited using the current input panel.
- **Create** tap to create the new connection. The successful message will display (Figure 6-4 on page 6-3).
- **Exit** tap to close the screen.



Figure 6-4. Connection Created

Tap OK to close the message and return to the main menu.

Cellular Power On

You need to turn on the cell phone power to dial to the Internet.



Figure 6-5. Cellular Power On

- *Cellular power on* check mark this item to turn the GSM on. Note that the Data Connection option becomes available.
- *Resume cellular power* check mark this option to have the GSM power turned on after a soft reset or switching the GRS-1 off.

Data Connection

This option is used for dialing the cell phone to reach the Internet. The Data Connection option is disabled if the GSM power is turned off.

Note that, if ActiveSync connection is established and the PC has an internet connection, then this connection will be selected.

The TPS Connection Manager creates new connections for "My ISP" predefined "network". When the user wants to connect to the Internet, Windows Mobile connection manager automatically selects the best available connection from dial-up connections to an Internet Service Provider.



Figure 6-6. My Internet Service Provider Connection

To make sure the connection is established, tap the status \blacksquare icon on the top of the screen. Tapping this arrows status icon displays the network status.

🚑 Start	# +€ @		
Connectivity	2:37 PM		
8	Wireless Manager		
ActiveSync	Connected		
Settings	Hide		
No tasks			
No upcoming appoi	ntments		
Live Search			
Device unlocked			
	🗏 🖲 💼		
Calendar	Contacts		

Figure 6-7. Connectivity Status

To check or modify the settings of the created network connection, you can use the standard Windows Mobile interface:

1. Select Settings on the Windows Mobile screen.



Figure 6-8. Settings

2. Select the **Connections** tab and then the **Connections** icon.



Figure 6-9. Connections

3. You will see **My ISP** connections. If there is no **My ISP** network listed, then tap the **Advanced** tab and select **My ISP** as an active network.



Figure 6-10. Settings - My ISP

You can also open the Internet Explorer on the Windows Mobile to check on the Internet availability (Figure 6-11 on page 6-7).

🏄 Internet Explorer 🛛 🗹 🗱 🍕 🗄	×
🗃 file://\windows\default_0409.htm 👻	1
	•
Y	=
Favorites 🛛 🕹	
	Ľ
1231 2 3 4 5 6 7 8 9 0 0 - = Tab q w e r t y u i o p [CAP] a s d f g h j k ; ; Shift z x c v b n m , / 4 Cti śu ` \	
Favorites 🔤 🔶 Menu	

Figure 6-11. Internet Explorer

GPS Receiver Power

Tap the TPS Connection Manager Icon in the lower left corner, and select **GPS Receiver Power** to turn on the GPS receiver in the GRS-1 system.



Figure 6-12. GPS Receiver Power

About the Tool

Select the About option from the main menu to view information about the TPS Connection Manager version.



Figure 6-13. About TPS Connection Manager

Notes:

Troubleshooting

This chapter will help you diagnose and solve some common problems you may encounter with the GRS-1.



Do not attempt to repair equipment yourself. Doing so may damage the hardware and will void your warranty.

Check This First!

Before contacting your Topcon dealer, check the following:

- If software is unresponsive, perform a software reset. See "Resetting the Software" on page 7-2 for details.
- Check all external connections (cable and wireless).
- Check all power sources for drained batteries or incorrectly connected batteries/cables.
- Check that the most current software is downloaded onto the GRS-1, and the most current firmware is loaded into the receiver. Check the TPS website (www.topconpositioning.com) for the latest updates.

Then, try the following:

- Reset the hardware. See "Resetting the Hardware" on page 7-3.
- Restore default settings for the Bluetooth module and GPS+ receiver. See "Restoring Bluetooth Module Defaults" on page 7-3 for details.
- Make sure the receiver is turned off, and remove the battery. Reinsert the battery and turn on the receiver.

If the problem persists, see the following sections for other solutions.

Troubleshooting Quick List

To reset the software, see "Resetting the Software" on page 7-2.

To reset the hardware, see "Resetting the Hardware" on page 7-3.

For power problems:

If "The GRS-1 does not power up" see page 7-5.

For general GRS-1 problems:

If "The GRS-1 is not receiving data (corrections) from an external receiver" see page 7-6.

If "Installed software and other data has been erased" see page 7-6.

For Bluetooth problems:

If "The GRS-1 is no longer connected via Bluetooth" see page 7-8.

If "You cannot connect to another Bluetooth-enabled device" see page 7-7.

Resetting the Software

Only perform a software reset in the following instances:

- To quit all active applications.
- After installing new applications.
- When there is no response after pressing a key or tapping on the screen.

When a software reset is performed, all running applications stop and unsaved data is lost; however, all installed programs and saved data is protected.

To perform a software reset:

1. Disconnect all cables and remove the inserted SD card.

2. Use the stylus pen to lightly press the software reset button at the upper section of the SD card slot (Figure 7-1).



Figure 7-1. Resetting the Software

Restoring Bluetooth Module Defaults

If the Bluetooth module is not performing as expected, try returning the settings to the defaults.

For the Bluetooth module, tap **Reset** on the **Accessibility** tab in BTManager.

Resetting the Hardware

If the GRS-1 does not operate after a software reset or the GRS-1 has become completely unresponsive, then perform a hardware reset. A hardware reset reverts all settings to defaults and erases data stored in RAM.



A hardware reset erases all RAM data.

To perform a hardware reset (Figure 7-2 on page 7-4):

- 1. Disconnect all cables and remove the inserted SD card.
- 2. Simultaneously hold the ENT and ESC buttons while pushing the software reset button with the stylus pen for ten or more seconds (Figure 7-2). The unit turns off.
- 3. Press the **Power** button.



Figure 7-2. Resetting the Hardware

Completely draining the battery performs the same function as a hardware reset.

When the hardware reset is performed, the registered information by applications to the OS are reset. In such a case, it is necessary to reset the time, and then reinstall applications.



If the equipment does not work normally after the hardware reset try reloading the operating system (see "OS Installation File" on page 8-2). Be aware that reloading the operating system erases all RAM and flash data, and programs installed on the device. Make sure to backup your data before you reload the operating system. If the problem continues, contact your Topcon dealer.

Charging/Powering Problems

The GRS-1 does not power up

- \Rightarrow The batteries may be discharged.
 - Connect the GRS-1 to a grounded outlet to charge the battery. See "Charging the Battery" on page 2-3.
 - Insert a fully charged battery. See "Installing the Battery" on page 2-2.
- \Rightarrow The charging cable may be disconnected or damaged.

Check that the cable is securely connected and undamaged.

➡ The GRS-1 may have a defective charger or defective internal battery.

If, after changing the battery or connecting an external power source, the GRS-1 still does not power up, contact TPS Customer Support for advice. See "Obtaining Technical Support" on page 7-8.

GRS-1 Problems

The following are some of the most commonly encountered problems with the GRS-1.

The GRS-1 is not receiving data (corrections) from an external receiver

- ➡ Check the Bluetooth LED. The LED will be blue when a connection has been established.
- \Rightarrow Check if BTManager was closed manually.

If BTManager was closed manually (tapping the close button on the title bar), the port used for communication between the GRS-1 and an external device will be disconnected from the Bluetooth module.

- 1. Open BTManager and check the Bluetooth Indicator:
- Red no connection between BTManager and the Bluetooth module.
- White a connection between BTManager and the Bluetooth module has been established.
- Green via a serial port, a connection between the GRS-1 and an external Bluetooth-enabled device has been established.
- 2. If needed, select the device to connect to, and tap **Connect**.

For more information, see "Connecting the GRS-1 and a Bluetooth Device" on page 3-3.

Installed software and other data has been erased

The battery in the GRS-1 has been completely drained or a hardware reset has been performed.

Reinstall all software. See "Installing Software" on page 2-10 and the software manual for details.

Restore data backed up from the CF card.

Bluetooth Problems

The following are some of the most commonly encountered problems with the GRS-1.

You cannot connect to another Bluetooth-enabled device

➡ If you encounter an error message while pairing with other Bluetooth-enabled devices, use Table 7-1 to learn which actions to take to correct the error.

Error Message	Action to Take
Win32 error ok Image: Win32 error The security account database contains an internal inconsistency. File: \BtDrtApi.cpp Line: 127 Function: BthPairRequest	 The PIN you entered on the My Bluetooth Device page does not match the PIN you entered on the remote device. Make sure the GRS-1 and the remote device use the same PIN. The Connectable setting was not selected on the remote device or the device was switched off. Make sure the remote device is on and the Connectable check box on the My Bluetooth Device page is selected. The remote Bluetooth device is already being used and it does not support simultaneous
	Bluetooth connections. Close the connection between the remote device and other device.
GRS-1 bt error OK × Confirming the condition (the connectable, security) of other devices.	Set the same parameters for authentication and encryption on both devices and try to connect again.
Win92 error This operation returned because the timeout period expired. OK	 The remote device does not support the Service Mode you selected. On the My Bluetooth Device page, select another Service Mode. There is a critical problem with the Bluetooth module.

Table 7-1. Most Common Errors

Error Message	Action to Take
Win32 error The specified network resource or device is no longer available. OK	Another application is using the GRS-1 COM2 serial port. Close the application or release the port. The COM2 serial port is reserved for the Bluetooth Manager.
Win32 error The device is not connected.	Port B of the GRS-1 GPS receiver, through which the Bluetooth Manager connects to the Bluetooth module, is not in command mode. Change Port B input mode back to command mode or clear the GRS-1 NVRAM. See the Operator's Manual for more information.

Table 7-1. Most Common Errors (Continued)

The GRS-1 is no longer connected via Bluetooth

Check the Bluetooth LED. The LED will be blue when a connection has been established.
 For information about connecting Bluetooth devices, see "Connecting the GRS-1 and a Bluetooth Device" on page 3-3

Obtaining Technical Support

Before contacting a Topcon customer representative about any problems with the receiver, see "Troubleshooting" on page 7-1 for some solutions that may fix the issue.

Contact your Topcon dealer or visit the Topcon Total Care Web site (www.TopconTotalCare.com) for technical support.



For quick and effective support, provide a detailed description of the problem.
When contacting Topcon for technical assistance, provide the following information for better and faster service:

- 1. A description of the following:
 - Field operation that was being performed when the problem occurred.
 - Details of the unexpected behavior, symptoms, and any error messages that preceded or follow the problem.
 - Problem occurrence frequency or patterns.
- 2. Receiver information and configuration settings. for receiver information, click Information in TRU, select **Save to File**, enter a file name, and save it to the computer.
- 3. Specifications of mobile devices and computers used in the field or office exhibiting the problem. These specifications should include model information, version number, operating system information, memory and storage capacity, etc.
- 4. Information about the system software, including the version number and steps to reproduce the problem.
- 5. A description of the field environment and/or observation conditions when the problem occurred.

Website

The Topcon website provides current information about Topcon's line of products. The support area of the website provides access to Topcon field and office software, manuals, frequently asked questions, and so forth. To access the Topcon website, visit www.topconpositioning.com.

The Topcon's TotalCare website also provides complete support, such as news, updates, reminders, training, live Webinars, and customer service to help you get the information you need. Visit www.topcontotalcare.com.

Updating the Operating System

This chapter will help you update the operating system (OS) on the GRS-1. Updating the operating system (OS) requires that the internal disk is formatted as part of the process which results in the complete loss of all files, registry settings, and user installed programs.



Formatting the internal disk results in the complete loss of all files, registry settings, and user installed programs.

Prior to updating the OS of the GRS-1, back up all registration codes, user data, TopSURV jobs, or any other data that is stored on the internal memory. Anything that is not part of the original OS will be erased and will not be recoverable.

Required Equipment

The following equipment is required to update the operating system.

- GRS-1
- GRS-1 Power Supply
- Operating System Installation File (GMSXWM.ROM)
- SD Card
- PC with ActiveSync Installed (for installing applications, e.g. TopSURV)
- GRS-1 USB Cable

OS Installation File

The OS installation file for the Topcon GRS-1 is titled **GMSXWM.ROM**. This file must be obtained from Topcon prior to proceeding.

Copy the OS installation file onto an SD card.

Format Reset

In order to update the OS, perform the following steps to enter the **Version up** (operating system update) screen.

- 1. Disconnect all cables and remove the SD card (if inserted).
- 2. Power on the GRS-1, and remove the battery while it is powered on.
- 3. When the GRS-1 is off, simultaneously hold the ESC and ENT buttons while pushing the software reset button with the stylus pen for two or more seconds (Figure 8-1 on page 8-3). The GRS-1 turns off.
- 4. Release the buttons.



Figure 8-1. format Reset

5. Simultaneously hold the ESC, Power, and Reset buttons until a black screen appears with text at the bottom that reads **DIAG start**, then release the buttons.

After **DIAG start** flashes on the screen, the **Version up** screen displays (Figure 8-2).

Version up
Windows Mobile> 1.00P132E
LJan 12 2008 10:48:001
<pre><mobm eboot="" ipl=""></mobm></pre>
MOBM V0.17A
EBoot UI 000
[Nov 25 2008 15:39:56]
IPL V1.06D
[Nov 25 2008 15:39:56]
(DIAG) V1.06A
[Nov 25 2008 16:13:03]
(FAST_RELOCATE)
<relocate></relocate>
END - AND FOTS CHELZEVERS

Figure 8-2. Version Up Screen

Installing the OS

- 1. Insert the SD card that contains the OS installation file.
- 2. Attach the external power supply. If you lose power during the OS update, the GRS-1 could become dysfunctional.
- 3. With Windows Mobile selected, press the ENT button.
- 4. Once the screen turns green to signify that the update is complete, press the ENT button as instructed.

- 5. Finally, press and hold ESC and POWER until the GRS-1 splash screen appears. This takes about 10 seconds.
- 6. Release the buttons and wait for the screen calibration process to display. It takes about 30 seconds for the device to reboot.

Troubleshooting

If the GRS-1 hangs at the GRS-1 splash screen indefinitely after an OS update, follow the steps below.

- 1. Perform a format reset as shown in "Format Reset" on page 8-2 to enter the **Version up** screen.
- 2. Attach the external power supply to the GRS-1.
- 3. Select the **RELOCATE** option in the **Version up** screen (Figure 8-2).
- 4. Press the ENT button.
- 5. This process will take a significant amount of time to complete. Once it is complete, insert the SD card that contains the OS installation file and install as outlined in "Installing the OS" on page 8-4.

Installing Applications

After the OS update is complete, reinstall and register all applications.

Specifications

The GRS-1, featuring Vanguard Technology, is a GNSS handheld receiver supporting 226 Universal Tracking channels, an internal computer running Windows Mobile operating system, an internal camera, a Bluetooth® wireless technology module, a Wireless LAN module, an electronic compass, and an SD card slot. The portable design and product integration allows this device to be a fullyfunctional, productive tool at any job.

GRS-1 Specifications

The following sections provide specifications for the GRS-1 and its internal components.

General Details

Table A-1 table lists the receiver's general specifications.

Physical	
Enclosure	Polycarbonate
Color	Topcon Yellow and Topcon Grey
Dimensions	W:93 x H:215 x D:53 mm
Weight	0.77 kg (with battery)
Antenna	Internal, GPS/GLONASS L1
Battery	Internal, rechargeable/replaceable Backup, replaceable

Table A-1. GRS-1 General Specifications

Controller	Integrated; uses Windows Mobile 6.1 Classic operating system
Keys (buttons)	Three keys: Power – On/Off ENT – applies settings, numerical values, and records points; shows Windows Start menu ESC – exits from the current screen or function
LEDs	Three LEDs: Bluetooth/Wireless LAN – indicates Bluetooth Wireless LAN connection status Cell Phone – indicates Cell Phone connection status Charge – indicates charge level
Environment	
Operating temperature	-20 C° to +50 C° with batteries -10 C° to +50 C° using camera
Storage temperature	-30 $^{\circ}$ to +60 $^{\circ}$ with batteries
Waterproof	IP66 at closing all connector caps. IPX4 (Weatherproof) at connecting external antenna cable.
Power	
Internal battery	Li-ion, 2500 mAh 7.4V; replaceable (BT-66Q)
Operating time	No less than 3.5 hours with GPS and cell phone use No less than 4 hours with GPS use No less than 9 hours without GPS and cell phone use
External power	1 port
Input voltage	8 to 15 V DC (for work) 10 to 15 V DC (for charge battery)
Output	12 V - 3 A
Consumption	5.3 W (with Windows Mobile and GPS and GSM)
Battery charger	Connect the AC adaptor to charge the power port. Available run charge when connected to a portable external source

Table A-1. GRS-1 General Specifications (Continued)

Charging time	within 5 hours for full charge
Charging Temperature	0°C to 40°C
On-board	Backup battery (CR2032) for timekeeping; replaceable button-type battery; 8–10 years normal operation
Communication	
Serial port	Port A of GPS+ board Baud rate = 460800, 230400, 115200, 2400, 1200, 600, 300 Flow control = RTC/CTS Length= 7, 8 (default) Stop bit= 1 default, 2 Parity= None (default), Odd, Even
Bluetooth	Version: Bluetooth standard 1.2; Class 2; Profile: SPP, DUP
Wireless LAN	Transmission specifications: IEEE802.11b/g Transmission method: Direct sequence spread spectrum (DS-SS) communication Access method: Infrastructure mode, Ad hoc mode Security: WEP(128/64bit), TKIP Frequency range: 2.4GHz (2,412~2,462MHz) (1~11ch) Transmission output: 30mW Transmission distance: 10m (In good visibility)
USB	Version 1.1 (mini B)
Cell Phone Modem	 Type: GSM/GPRS/EDGE CDMA for US (Verizon[™] Approved) WCDMA for Japan Protocol: GPRS, EDGE, CDMA, WCDMA Frequency: Quad Band 850,900,1800,1900MHz, CDMA800,1900MHz, WCDMA,2100MHz
Windows Mobile	
Processor	Marvel PXA320
Processor speed	806MHz
Operating System	Microsoft Windows® Mobile 6.1 Classic

Table A-1. GRS-1 General Specifications (Continued)

Digital Camera (Op	otional)
Pixel	2M (UXGA1600x1200)
Sensor element	1/4 inches color C-MOS sensor
Angle of View	53°x 40°
F number	3.0
Focus Range	90 cm to infinity (normal mode), 5 to 10 cm (macro mode)
Zoom	Digital zoom x2, x4, x8
Digital Compass	
Axis	Three (X,Y,Z)
Azimuth angle accuracy	+/-8 degree (in level after calibration)
Inclinometer	
Axis	Two (X,Y)
Angle range	+/- 30 degrees
Tilt angle accuracy	+/- 2 degrees (with reference to optical axis of distance meter)
LCD Display	
Size	640x480 VGA (portrait/landscape) 3.7 inch color TFT transmissive type
Backlight	LED
Touch screen	Resistive touch screen; passive
Audio	
Speaker	Mono
Microphone	Mono
Memory	
ROM	1 GB (NAND Flash Memory)

Table A-1.	GRS-1	General	Specifications	(Continued)
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RAM	256 MB (DDR2 SD RAM)	
Connectors and Slot		
Serial port	RS-232 (mini) port for communication with the internal GNSS board (port A)	
USB port	1 port for Windows Mobile; type B mini ver 1.1; connect to PC using ActiveSync	
External power port	1 port; DC Jack type A; for connecting the AC adaptor or external battery	
External antenna connector	Lemo connector (EPS.01.250.DLN); 5 VDC output to external antenna	
SD card slot	1 slot for memory storage and I/O	

Table A-1. GRS-1 General Specifications (Continued)

GPS Details

Table A-2 lists the GPS board's general specifications.

Table	A-2.	GPS	Board	Specifications
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Tracking Specifica	tions
Tracked Signals ^a	GPS/GLONASS, L1 C/A Code & Carrier, GPS L2C WASS/EGNOS/MSAS
Receiver Type	G – GPS L1 GD – GPS L1/L2 GGD – GPS/GLONASS L1/L2
Number of Channels	226 channels ^b incorporates Topcon's exclusive Universal Tracking Channel Technology
Cold Start Warm Start Reacquisition	< 30 sec < 10 sec < 1 sec
Survey Accuracy ^c	

Static	For L1 – H: 3mm + 0.8ppm (x baseline length); V: 4mm + 1.0ppm (x baseline length) For L1 +L2– H: 3mm + 0.5ppm (x baseline length); V: 5mm + 0.5ppm (x baseline length)
Kinematic, RTK	For L1/L1 +L2 – H: 10mm + 1.0ppm (x baseline length); V: 15mm + 1.0ppm (x baseline length)
DGPS	Post processing/RTCM: typically less than 0.5m (RMS)
Other (GPS)	
Real time data format	RTCM 2.3, 3.0; CMR, CMR+ ^d ; TPS
Real time data format NMEA	RTCM 2.3, 3.0; CMR, CMR+ ^d ; TPS NMEA 2.2, 2.3, 3.0
Real time data format NMEA Output rate	RTCM 2.3, 3.0; CMR, CMR+ ^d ; TPS NMEA 2.2, 2.3, 3.0 Up to 10 Hz ^e
Real time data format NMEA Output rate RTK initialize time	RTCM 2.3, 3.0; CMR, CMR+ ^d ; TPS NMEA 2.2, 2.3, 3.0 Up to 10 Hz ^e 5 seconds ^f or less

Table A-2. GPS Board Specifications (Continued)

a. The GRS-1 includes the latest Vanguard ASIC technology and is capable of supporting planned signals for Galileo. Support for Galileo will be incorporated into the GRS-1 when the constellation is ready for commercial use.

- b. Vanguard ASIC includes two dedicated channels for L-Band tracking. The GRS-1 receiver does not support L-Band signal tracking.
- c. Accuracy will vary depending on the number of satellites used, obstructions, satellite geometry (PDOP), occupation time, multipath effects, and atmospheric conditions. Performance may be degraded in conditions with high ionospheric activity, extreme multipath, or under dense foliage. For maximum system accuracy, always follow best practices for GNSS data collections.
- d. CMR/CMR+ is a third-party proprietary format. Use of this format is not recommended and performance cannot be guaranteed. Use of industry standard RTCM 3.x is always recommended for optimal performance.
- e. More than 10 Hz operation may be supported for custom applications. For more information, contact your dealer.
- f. Depending on the base line length, number of tracked satellites, and multipath and atmospheric conditions.

Bluetooth Details

Table A-3 lists the GPS board's general specifications.

Transmission	
Version	Bluetooth® 1.2
Method	Frequency hopping spread spectrum (FH-SS) communication
Distance	5m (in good visibility) ^a
Speed	1 Mbps (max.)
Other (Bluetooth)	
Modulation Method	GFSK
Antenna	Internal Chip Antenna
Frequency Range	2.4 GHz (2,402 - 2,480 MHz) (0-78 ch)
Corresponding Profile	SPP, DUN

Table A-3. Bluetooth Specifications

a. Transmission distance will be affected by environmental factors. Radio wave distance may be narrowed near reinforced concrete buildings and large metallic furniture.

Connector Specifications

The GRS-1 has one antenna connector for radio transmission/ reception and three port connectors for power and data upload/ download.

Serial Connector

The serial connector (Figure A-1) is a sealed receptacle, 5 pin, port. This connector is configured as port A of the internal GPS receiver.



Figure A-1. Serial RS232 Connector

Table A-4 gives the serial port's pin specifications.

Table A-4. Serial Pin Specifications

Number	Signal Name	Dir	Details
1	TXD	0	Clear to send
2	RXD	Ι	Request to send
3	GND	-	Signal ground
4	GND	-	Signal ground
5	-	-	Not used

USB Connector

Rimmed in yellow, the USB connector is a sealed receptacle, 4 pin TPS cable connector (Figure A-2).



Figure A-2. USB Connector for GGD Options

Table A-5 gives the USB connector specifications.

Number	Signal Name	Dir	Details
1	VDD	Р	Bus power input
2	V-	I/O	Data minus
3	V+	I/O	Data plus
4	-	-	Not used
5	GND	-	Ground

Table A-5. USB Specifications

Product Identification

Earlier versions of the GRS-1 receiver only support 72 Universal Tracking channels. GRS-1 receivers, featuring Vanguard Technology[™], support 226 Universal Tracking channels and are listed in Table B-1 by serial number range.

Cellular Modem	Serial Number	
GRS-1 (With Camera)		
No modem	594-2xxxx	
GSM modem	595-2xxxx	
CDMA modem (Verizon [™] approved)	822-2xxxx	
WCDMA modem (Japan only)	803-2xxxx	
GRS-1N (Without Camera)		
No modem	824-2xxxx	
GSM modem	825-2xxxx	
CDMA modem (Verizon [™] approved)	827-2xxxx	
WCDMA modem (Japan only)	826-2xxxx	

Table B-1. Product Serial Numbers

Safety Warnings

General Warnings



TPS receivers are designed for survey and survey related uses (that is, surveying coordinates, distances, angles and depths, and recording such measurements). This product should never be used:

- Without the user thoroughly understanding this manual.
- After disabling safety systems or altering the product.
- With unauthorized accessories.
- Without proper safeguards at the survey site.
- Contrary to applicable laws, rules, and regulations.
- Used near flammable gas, liquid matter, or in a coal mine.



TPS receivers should never be used in dangerous environments. Use in rain or snow for a limited period is permitted.



To avoid electric shock, do not connect or disconnect equipment with wet hands.

Battery Pack Warnings



Never attempt to open the casing of the removable battery! Lithium-Ion batteries can be dangerous if mishandled!



Do not incinerate or heat battery above 212° fahrenheit (100° celsius). Excessive heat can cause serious damage and possible explosion.



Tampering with the batteries by end users or nonfactory authorized technicians will void the battery's warranty.

- Do not attempt to open the battery pack or replace it.
- Do not disassemble the battery pack.
- Do not charge in conditions different than specified.
- Do not use other than the specified battery charger.
- Do not short circuit.
- Do not crush or modify.
- Do not cover the charger while it is charging the battery.
- Do not use a wet battery or charger.



Do not allow skin or clothing to come into contact with acid from the batteries. If this does occur, then wash off with water and seek medical advice.



Do not touch the charger, AC-DC converter or a heated part of the device for a long period while charging the battery. There is a risk of lowtemperature burn.

Usage Warnings



If this product has been dropped, altered, transported or shipped without proper packaging, or otherwise treated without care, erroneous measurements may occur.

The owner should periodically test this product to ensure it provides accurate measurements.

Inform TPS immediately if this product does not function properly.



Only allow authorized TPS warranty service centers to service or repair this product.

Regulatory Information

The following sections provide information on this product's compliance with government regulations for use.

FCC Compliance

The Federal Communication Commission Radio Frequency Interference Statement includes the following paragraph:

This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to Part 15 of FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates, uses, and can radiate radio frequency energy. If not installed and used in accordance with the instructions, it may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by tuning the equipment off and on, the user is encouraged to try and correct the interference by one or more of the following measures:

- Reorient or relocate the receiving antenna.
- Increase the distance between the equipment and the receiver.
- Connect the equipment to outlet on a circuit different from that to which the receiver is connected.
- Consult the dealer or an experienced radio/TV technician for help.

Any changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment.

Federal Communication Commission Declaration of Conformity (DoC) Statement



Model No: GRS-1

Trade Name	Topcon
Responsible Party	Topcon Positioning
	Systems, Inc.
Address	7400 National Drive,
	Livermore, CA 94550
Telephone No	925-245-8300

Industry Canada (IC) Regulatory Information

This equipment complies with IC radiation exposure limits set forth for uncontrolled equipment and meets RSS-102 of the IC radio frequency (RF) exposure rules. This equipment has very low levels of RF energy that it deemed to comply without maximum permissive exposure evaluation (MPE). But it is desirable that it should be installed and operated with a least 20cm and more between the radiator and person's body (excluding extremities: hands, wrists, feet, and ankles)

This Class B digital apparatus meets all requirements of the Canadian Interference-Causing Equipment Regulations.

Cet appareil numérique de la classe B respecte conform a la norme NMB-003 du Canada.

This device complies with RSS 210 of Industry Canada.

Operation is subject to the following two conditions:

- (1) This device may not cause interference, and
- (2) This device must accept any interference, including

interference that may cause undesired operation of this device.

L ' utilization de ce dispositif est autorisée seulement aux conditions suivantes :

(1) il ne doit pas produire de brouillage et

(2) l' utilisateur du dispositif doit étre prêt à accepter tout

brouillage radioélectrique reçu, même si ce brouillage est susceptible de compromettre le fomctionnement du dispositif.

FCC/IC RF Radiation Exposure Statement For Bluetooth and 802.11b/g

To comply with FCC/IC RF exposure compliance requirements, this device must not be co-located or operating in conjunction with any other antenna or transmitter.

For mobile operation, To comply with FCC/IC RF exposure compliance requirements, a separation distance of at least 20cm must be maintained between the antenna of this device and all persons. This device must not be co-located or operating in conjunction with any other antenna or transmitter.

The installer of this device must ensure that the antenna is located or pointed such that it does not emit RF field in excess of Health Canada limits for the general population; consult Safety Code 6, obtainable from Health Canada's website at www.hc-sc.gc.ca/rpb.

In case that the option GSM/GPRS/EDGE/UMTS/HSDPA Module (FCC ID: QIPHC25, IC: 267W-HC25) is installed To comply with FCC/IC RF exposure compliance requirements, this device has been demonstrated co-location compliance requirement with GSM/GPRS/EDGE/UMTS/HSDPA Module FCC ID: QIPHC25 & IC: 267W-HC25, which is an option for GRS. This device must not be co-located in conjunction with any other antenna or transmitter.

For mobile operation, To comply with FCC/IC RF exposure compliance requirements, a separation distance of at least 20cm must be maintained between the GSM antenna provided together with GSM/GPRS/EDGE/UMTS/HSDPA Module FCC ID: QIPHC25 & IC: 267W-HC25 and all persons as well as between the antenna of this device and all persons.

European Community Declaration of Conformity with R&TTE Directive 1999/5/EC

The following standards were applied: (R&TTE Directive 1999/5/ EEC)

- EN 301 489-1 v1.8.1
- EN 301 489-7 v1.3.1
- EN 301 489-17 v1.2.1
- EN 301 489-24 v1.4.1
- EN 300 328 v1.7.1
- EN 301 511 v9.0.2
- EN 301 908-1 v4.2.1
- EN 301 908-2 v4.2.1
- EN 50371:2002
- EN 60950-1:2006+A11:2009 & A1:2010

The following CE mark is affixed to the device:

€€

The equipment is labelled with an CE! mark that informs users when equipment is used with the (RH-1) Radio Holder with a UHF radio modem. The UHF frequency range (410-470 MHz) is not harmonized throughout Europe and the specific country spectrum authority should be notified before a radio modem is used.

This equipment is intended to be marketed in the following countries:

List of National Codes:

- AT DE MT GB
- BE GR NL IS
- CY HU PL LI
- CZ IE PT NO
- DK IT SK CH

- EE LV SI BG
- FILT ES RO
- FR LU SE TR

Declaration of Conformity with Regard to the R&TTE Directive 1999/5/EC

ၒၭႍČesky [Czech]	(<i>Topcon Positioning Systems, Inc.</i>) tímto prohlašuje, že tento (<i>GRS</i>) je ve shodě se základními požadavky a dalšími příslušnými ustanoveními směrnice 1999/5/ES.
da Dansk [Danish]	Undertegnede (Topcon Positioning Systems, Inc.) erklærer herved, at følgende udstyr (GRS) overholder de væsentlige krav og øvrige relevante krav i direktiv 1999/5/EF.
de Deutsch [German]	Hiermit erklärt (<i>Topcon Positioning Systems, Inc.</i>) dass sich das Gerät (<i>GRS</i>) in Übereinstimmung mit den grundlegenden Anforderungen und den übrigen einschlägigen Bestimmungen der Richtlinie 1999/5/EG befindet.
et]Eesti [Estonian]	Käesolevaga kinnitab (<i>Topcon Positioning Systems, Inc.</i>) seadme (<i>GRS</i>) vastavust direktiivi 1999/5/EÜ põhinõuetele ja nimetatud direktiivist tulenevatele teistele asjakohastele sätetele.
en English	Hereby, (Topcon Positioning Systems, Inc.) declares that this (GRS) is in compliance with the essential requirements and other relevant provisions of Directive 1999/5/EC.
ि Español [Spanish]	Por medio de la presente (<i>Topcon Positioning Systems, Inc.</i>) declara que el (<i>GRS</i>) cumple con los requisitos esenciales y cualesquiera otras disposiciones aplicables o exigibles de la Directiva 1999/5/CE.

<u>ຍ</u> ີ Ελληνική [Greek]	ΜΕ ΤΗΝ ΠΑΡΟΥΣΑ (Topcon Positioning Systems, Inc.) ΔΗΛΩΝΕΙ ΟΤΙ (GRS) ΣΥΜΜΟΡΦΩΝΕΤΑΙ ΠΡΟΣ ΤΙΣ ΟΥΣΙΩΔΕΙΣ ΑΠΑΙΤΗΣΕΙΣ ΚΑΙ ΤΙΣ ΛΟΙΠΕΣ ΣΧΕΤΙΚΕΣ ΔΙΑΤΑΞΕΙΣ ΤΗΣ ΟΔΗΓΙΑΣ 1999/5/ΕΚ.
[fr]Français [French]	Par la présente (<i>Topcon Positioning Systems, Inc.</i>) déclare que l'appareil (<i>GRS</i>) est conforme aux exigences essentielles et aux autres dispositions pertinentes de la directive 1999/5/CE.
[it]Italiano [Italian]	Con la presente (<i>Topcon Positioning Systems, Inc.</i>) dichiara che questo (<i>GRS</i>) è conforme ai requisiti essenziali ed alle altre disposizioni pertinenti stabilite dalla direttiva 1999/5/CE.
ાં Ελληνική [Greek]	ΜΕ ΤΗΝ ΠΑΡΟΥΣΑ (Topcon Positioning Systems, Inc.) ΔΗΛΩΝΕΙ ΟΤΙ (GRS) ΣΥΜΜΟΡΦΩΝΕΤΑΙ ΠΡΟΣ ΤΙΣ ΟΥΣΙΩΔΕΙΣ ΑΠΑΙΤΗΣΕΙΣ ΚΑΙ ΤΙΣ ΛΟΙΠΕΣ ΣΧΕΤΙΚΕΣ ΔΙΑΤΑΞΕΙΣ ΤΗΣ ΟΔΗΓΙΑΣ 1999/5/ΕΚ.
[fr] Français [French]	Par la présente (<i>Topcon Positioning Systems, Inc.</i>) déclare que l'appareil (<i>GRS</i>) est conforme aux exigences essentielles et aux autres dispositions pertinentes de la directive 1999/5/CE.
[it] Italiano [Italian]	Con la presente (<i>Topcon Positioning Systems, Inc.</i>) dichiara che questo (<i>GRS</i>) è conforme ai requisiti essenziali ed alle altre disposizioni pertinenti stabilite dalla direttiva 1999/5/CE.
Latviski [Latvian]	Ar šo (<i>Topcon Positioning Systems, Inc.</i>) deklarē, ka (<i>GRS</i>) atbilst Direktīvas 1999/5/EK būtiskajām prasībām un citiem ar to saistītajiem noteikumiem.
Lietuvių [Lithuanian]	Šiuo (<i>Topcon Positioning Systems, Inc.</i>) deklaruoja, kad šis (<i>GRS</i>) atitinka esminius reikalavimus ir kitas 1999/5/EB Direktyvos nuostatas.
nl Nederlands [Dutch]	Hierbij verklaart (<i>Topcon Positioning Systems,</i> <i>Inc.</i>) dat het toestel (<i>GRS</i>) in overeenstemming is met de essentiële eisen en de andere relevante bepalingen van richtlijn 1999/5/EG.
[mt] Malti [Maltese]	Hawnhekk, (Topcon Positioning Systems, Inc.), jiddikjara li dan (GRS) jikkonforma mal-htiģijiet essenzjali u ma provvedimenti ohrajn relevanti li hemm fid-Dirrettiva 1999/5/EC.
hu Magyar [Hungarian]	Alulírott, (Topcon Positioning Systems, Inc.) nyilatkozom, hogy a (GRS) megfelel a vonatkozó alapvető követelményeknek és az 1999/5/EC irányelv egyéb előírásainak.

Polski [Polish]	Niniejszym, (Topcon Positioning Systems, Inc.), deklaruję, że (GRS) spełnia wymagania zasadnicze oraz stosowne postanowienia zawarte Dyrektywie 1999/5/EC.
[만]Português [Portuguese]	(<i>Topcon Positioning Systems, Inc.</i>) declara que este (<i>GRS</i>) está conforme com os requisitos essenciais e outras disposições da Directiva 1999/5/CE.
्री Slovensko [Slovenian]	(Topcon Positioning Systems, Inc.) izjavlja, da je ta (GRS) v skladu z bistvenimi zahtevami in ostalimi relevantnimi določili direktive 1999/5/ES.
Slovensky [Slovak]	<i>(Topcon Positioning Systems, Inc.)</i> týmto vyhlasuje, že <i>(GRS)</i> spĺňa základné požiadavky a všetky príslušné ustanovenia Smernice 1999/5/ES.
fi]Suomi [Finnish]	(Topcon Positioning Systems, Inc.) vakuuttaa täten että (GRS) tyyppinen laite on direktiivin 1999/5/EY oleellisten vaatimusten ja sitä koskevien direktiivin muiden ehtojen mukainen.
ङ्णSvenska [Swedish]	Härmed intygar (Topcon Positioning Systems, Inc.) att denna (GRS) står I överensstämmelse med de väsentliga egenskapskrav och övriga relevanta bestämmelser som framgår av direktiv 1999/5/EG.

Community of Europe Compliance

The product described in this manual is in compliance with the R&TTE and EMC directives from the European Community.



WEEE Directive

This symbol is applicable to EU members states only.

Following information is only for EU-member states:

The use of the symbol indicates that this product may not be treated as household waste. By ensuring this product is disposed of correctly, you will help prevent potential negative consequences for the environment and human health, which could otherwise be caused by inappropriate waste handling of this product. For more detailed information about the take-back and recycling of this product, please contact your supplier where you purchased the product or consult.



EU Battery Directive

This symbol is applicable to EU members states only.

Battery users must not dispose of batteries as unsorted general waste, but treat properly.



Perchlorate Material – Special Handling May Apply

For more information, see www.dtsc.ca.gov/ hazardouswaste/perchlorate

This applies to California, USA only.

Warranty Terms

TPS laser and electronic positioning equipment are guaranteed against defective material and workmanship under normal use and application consistent with this Manual. The equipment is guaranteed for the period indicated, on the warranty card accompanying the product, starting from the date that the product is sold to the original purchaser by TPS' Authorized Dealers.¹

During the warranty period, TPS will, at its option, repair or replace this product at no additional charge. Repair parts and replacement products will be furnished on an exchange basis and will be either reconditioned or new. This limited warranty does not include service to repair damage to the product resulting from an accident, disaster, misuses, abuse or modification of the product.

Warranty service may be obtained from an authorized TPS warranty service dealer. If this product is delivered by mail, purchaser agrees to insure the product or assume the risk of loss or damage in transit, to prepay shipping charges to the warranty service location and to use the original shipping container or equivalent. A letter should accompany the package furnishing a description of the problem and/ or defect.

The purchaser's sole remedy shall be replacement as provided above. In no event shall TPS be liable for any damages or other claim including any claim for lost profits, lost savings or other incidental or consequential damages arising out of the use of, or inability to use, the product.

^{1.} The warranty against defects in a Topcon battery, charger, or cable is 90 days.

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Topcon Positioning Systems, Inc.

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